

4.1. The Langevin Equation

Langevin equation is a first order in time stochastic differential equation of the form

$$\dot{q}_i(t) = -\frac{1}{2} f_i[\mathbf{q}(t)] + v_i(t) \quad \left(\dot{q}_i = \frac{dq_i}{dt} \right) \quad (4.1)$$

where $\mathbf{q} \in R^d$ & \mathbf{v} is a set of d stochastic functions called “noise” with a functional probability distribution $[d\rho(\mathbf{v})]$, which we shall assume to be gaussian.

$$[d\rho(\mathbf{v})] = [d\mathbf{v}] \exp\left[-\frac{1}{2\Omega} \int_{-\infty}^{\infty} dt \sum_{i=1}^d v_i^2(t)\right] \quad (4.2)$$

where Ω is the width of the noise.

Dividing the interval $(-T, T)$ into $2N$ segments of length ε , we have $\varepsilon = T/N$. Eq(4.2) can be written in discretized form as

$$\begin{aligned} [d\rho(\mathbf{v})] &= [d\mathbf{v}] \exp\left[-\frac{\varepsilon}{2\Omega} \sum_{i=1}^d \sum_{k=-N}^N v_i^2(t_k)\right] \quad (T, N \rightarrow \infty) \\ &= [d\mathbf{v}] \prod_{i=1}^d \prod_{k=-N}^N \exp\left[-\frac{\varepsilon}{2\Omega} v_i^2(t_k)\right] \end{aligned}$$

where

$$t_k = k\varepsilon$$

Using

$$\int_{-\infty}^{\infty} dx \exp\left(-\frac{1}{2} ax^2\right) = \sqrt{\frac{2\pi}{a}}$$

we see that the normalization

$$1 = \int [d\rho(\mathbf{v})] = C \prod_{i=1}^d \left(\int \prod_{k=-N}^{N-1} dv_i(t_k) \exp\left[-\frac{\varepsilon}{2\Omega} v_i^2(t_k)\right] \right)$$

requires

$$[d\mathbf{v}] = \left(\frac{\varepsilon}{2\pi\Omega}\right)^{dN} \prod_{i=1}^d \int \prod_{k=-N}^{N-1} dv_i(t_k) \quad (4.2a)$$

with $N \rightarrow \infty$ & $\varepsilon \rightarrow 0$ understood.

This particular form of the gaussian noise, called gaussian white noise, is related to Markov's processes (see Appendix A4).

Note that Ω can be absorbed as follows. Setting

$$\tau = \Omega t \quad w_i(\tau) = \frac{1}{\Omega} v_i(t) \quad F_i = \frac{f_i}{\Omega}$$

we have

$$[d\rho(\mathbf{w})] = [d\mathbf{w}] \exp\left[-\frac{1}{2} \int d\tau \sum_i w_i^2(\tau)\right]$$

$$\& \quad \dot{q}'_i(\tau) = -\frac{1}{2} F_i[\mathbf{q}(\tau)] + w_i(\tau) \quad \left(\dot{q}'_i = \frac{dq'_i}{d\tau} \right)$$

Gaussian noise can also be characterized by its 1- & 2-point correlation functions:

$$\langle v_i(t) \rangle = 0 \quad \langle v_i(t) v_j(t') \rangle = \Omega \delta_{ij} \delta(t-t') \quad (4.3)$$

Proof:

Using eq(4.2a), we have

$$\langle v_i(t) \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right)^{dN} \prod_{m=1}^d \int_{-\infty}^{\infty} \prod_{k=-N}^{N-1} d v_m(t_k) \left(v_i(t) \exp \left[-\frac{\varepsilon}{2\Omega} v_m^2(t_k) \right] \right)$$

For $m \neq i$, each integral gives a factor $\left(\frac{2\pi\Omega}{\varepsilon} \right)^{1/2}$ so that we're left with

$$\langle v_i(t) \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right)^N \int_{-\infty}^{\infty} \prod_{k=-N}^{N-1} d v_i(t_k) \left(v_i(t) \exp \left[-\frac{\varepsilon}{2\Omega} v_i^2(t_k) \right] \right)$$

Let $t = t_p$, then for all $k \neq p$, each integral gives a factor $\left(\frac{2\pi\Omega}{\varepsilon} \right)^{1/2}$ & we have

$$\langle v_i(t) \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right)^{1/2} \int_{-\infty}^{\infty} d v_i(t_p) \left(v_i(t_p) \exp \left[-\frac{\varepsilon}{2\Omega} v_i^2(t_p) \right] \right)$$

Using

$$\int_{-\infty}^{\infty} d x x \exp \left(-\frac{1}{2} a x^2 \right) = 0$$

we have

$$\langle v_i(t) \rangle = 0$$

thus proving the 1st part of eq(4.3).

Similarly,

$$\langle v_i(t) v_j(t') \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right)^{dN} \prod_{m=1}^d \int_{-\infty}^{\infty} \prod_{k=-N}^{N-1} d v_m(t_k) \left(v_i(t) v_j(t') \exp \left[-\frac{\varepsilon}{2\Omega} v_m^2(t_k) \right] \right)$$

For $m \neq i$ or j , each integral gives a factor $\left(\frac{2\pi\Omega}{\varepsilon} \right)^{1/2}$ so that we're left with

$$\langle v_i(t) v_j(t') \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right)^{2N} \int_{-\infty}^{\infty} \prod_{k=-N}^{N-1} d v_i(t_k) d v_j(t_k) \left(v_i(t) v_j(t') \exp \left[-\frac{\varepsilon}{2\Omega} (v_i^2(t_k) + v_j^2(t_k)) \right] \right)$$

Let $t = t_p$ & $t' = t_q$, then for all $k \neq p$ or q , each integral gives a factor $\left(\frac{2\pi\Omega}{\varepsilon} \right)^{1/2}$ & we have

$$\langle v_i(t) v_j(t') \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right) \int_{-\infty}^{\infty} d v_i(t_p) d v_j(t_q) \left(v_i(t_p) v_j(t_q) \exp \left[-\frac{\varepsilon}{2\Omega} (v_i^2(t_p) + v_j^2(t_q)) \right] \right)$$

Using

$$\int_{-\infty}^{\infty} d x x \exp \left(-\frac{1}{2} a x^2 \right) = 0 \qquad \int_{-\infty}^{\infty} d x x^2 \exp \left(-\frac{1}{2} a x^2 \right) = \sqrt{\frac{2\pi}{a^3}}$$

we have

$$\begin{aligned} \langle v_i(t) v_j(t') \rangle &= \delta_{ij} \delta_{pq} \left(\frac{\varepsilon}{2\pi\Omega} \right)^{1/2} \int_{-\infty}^{\infty} d v_i(t_p) v_i(t_p)^2 \exp \left[-\frac{\varepsilon}{2\Omega} v_i^2(t_p) \right] \\ &= \delta_{ij} \delta_{pq} \frac{\Omega}{\varepsilon} \\ &= \delta_{ij} \begin{cases} \frac{\Omega}{\varepsilon} & \text{for } -\frac{\varepsilon}{2} < t - t' < \frac{\varepsilon}{2} \\ 0 & \text{otherwise} \end{cases} \\ &= \delta_{ij} \begin{cases} \frac{N\Omega}{T} & \text{for } -\frac{T}{2N\Omega} < \frac{t-t'}{\Omega} < \frac{T}{2N\Omega} \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

Using [see,e.g., G.B.Arken, "Mathematical Methods for Physicists", (index: delta function, sequence)]

$$\delta_n(x) = \begin{cases} n & \text{for } -\frac{1}{2n} < x < \frac{1}{2n} \\ 0 & \text{otherwise} \end{cases} \quad \rightarrow \quad \lim_{n \rightarrow \infty} \delta_n(x) = \delta(x)$$

we have

$$\langle v_i(t) v_j(t') \rangle = \delta_{ij} \delta\left(\frac{t-t'}{\Omega}\right) = \delta_{ij} \Omega \delta(t-t')$$

which is the 2nd part of eq(4.3).

Note: One should go over the above derivation to convince oneself that one can use the gaussian integral properties to write down immediately, without going through the intermediate steps, that

$$\langle v_i(t) v_j(t') \rangle = \left(\frac{\varepsilon}{2\pi\Omega} \right) \int_{-\infty}^{\infty} d v_i(t) d v_j(t') \left(v_i(t) v_j(t') \exp\left[-\frac{\varepsilon}{2\Omega} (v_i^2(t) + v_j^2(t'))\right] \right) \quad (4.3a)$$

Given $\mathbf{q}(t_0) = \mathbf{q}_0$, the probability distribution of finding $\mathbf{q}(t) = \mathbf{q}$ is defined as

$$P(\mathbf{q}, t; \mathbf{q}_0, t_0) = \left\langle \prod_{i=1}^d \delta[q_i(t) - q_i] \right\rangle_{\nu} \quad (t \geq t_0) \quad (4.4)$$

where the subscript ν denotes the gaussian distribution eq(4.2) and $\mathbf{q}(t)$ obeys the Langevin eq(4.4).

For any function $O(\mathbf{q})$,

$$\langle O[\mathbf{q}(t)] \rangle_{\nu} = \int d\mathbf{q} P(\mathbf{q}, t; \mathbf{q}_0, t_0) O(\mathbf{q})$$

(4.5)

Since the Langevin eq. is local in time, P is Markovian with

$$P(\mathbf{q}_3, t_3; \mathbf{q}_1, t_1) = \int d\mathbf{q}_2 P(\mathbf{q}_3, t_3; \mathbf{q}_2, t_2) P(\mathbf{q}_2, t_2; \mathbf{q}_1, t_1) \quad (t_3 \geq t_2 \geq t_1) \quad (4.6)$$

In terms of the bra-ket notation, we define

$$P(\mathbf{q}, t; \mathbf{q}_0, t_0) \equiv \langle \mathbf{q} | P(t, t_0) | \mathbf{q}_0 \rangle \quad (4.7)$$

Since eq(4.4) is invariant under time translation,

$$P(\mathbf{q}, t; \mathbf{q}_0, t_0) = P(\mathbf{q}, \mathbf{q}_0; t - t_0)$$

$$\rightarrow P(t, t_0) = P(t - t_0)$$

Hence, there exists an operator H such that

$$P(t, t_0) = e^{-(t-t_0)H}$$

(4.8)

H is known as the Fokker-Planck hamiltonian.

Note: Sometimes we'll omit the initial data & simplify the notation by writing $P(\mathbf{q}, t; \mathbf{q}_0, t_0)$ simply as $P(\mathbf{q}, t)$.