

4.4. Sigma Model

Real K-G field:

$$\mathcal{L} = \frac{1}{2} f \left(\partial_\mu \phi \cdot \partial^\mu \phi + v \phi^2 - \frac{1}{2} g \phi^4 \right)$$

$$v \phi^2 - \frac{1}{2} g \phi^4 = -\frac{1}{2} g \left(\phi^2 - \frac{v}{g} \right)^2 + \frac{v^2}{2g}$$

$$= -\frac{1}{2} g (\phi^2 - v^2)^2 + \frac{1}{2} g v^4$$

$$(v = \sqrt{\frac{Y}{g}})$$

$$\rightarrow \mathcal{L} = \frac{1}{2} f \left(\partial_\mu \phi \cdot \partial^\mu \phi - \frac{1}{2} g (\phi^2 - v^2)^2 + \frac{1}{2} g v^4 \right)$$

Dropping the irrelevant constant term, we have

$$\mathcal{L} = \frac{1}{2} f \left(\partial_\mu \phi \cdot \partial^\mu \phi - \frac{1}{2} g (\phi^2 - v^2)^2 \right)$$

For a set of N real fields, let

$$\boldsymbol{\phi} = (\phi_1, \dots, \phi_N)$$

$$\rightarrow \sum_{a=1}^N \phi_a^2 = \boldsymbol{\phi} \cdot \boldsymbol{\phi} = \phi^2$$

Sigma model:

$$\mathcal{L} = \frac{1}{2} f \left(\partial_\mu \boldsymbol{\phi} \cdot \partial^\mu \boldsymbol{\phi} - \frac{1}{2} g (\boldsymbol{\phi}^2 - v^2)^2 \right)$$

Note:

$$\mathcal{L} \neq \sum_{a=1}^N \mathcal{L}(\phi_a) \quad \text{since} \quad \sum_{a=1}^N \phi_a^4 \neq \phi^4$$

$$\mathcal{H} = \frac{1}{2} f \left(\frac{1}{c^2} \dot{\boldsymbol{\phi}}^2 + \nabla \boldsymbol{\phi} \cdot \nabla \boldsymbol{\phi} + \frac{1}{2} g (\boldsymbol{\phi}^2 - v^2)^2 \right)$$

$$\mathcal{H}_P = \frac{1}{4} f g (\boldsymbol{\phi}^2 - v^2)^2$$

Let $U^T U = I$
 $\boldsymbol{\phi} \rightarrow U \boldsymbol{\phi}$ is an $O(N)$ transformation

Since $\boldsymbol{\phi}^2 = \boldsymbol{\phi}^T \boldsymbol{\phi} \rightarrow \boldsymbol{\phi}^T U^T U \boldsymbol{\phi} = \boldsymbol{\phi}^2$,
 $\therefore \mathcal{L} \rightarrow \mathcal{L}$ (invariant)

Let

$$\boldsymbol{\phi} = \mathbf{v} + \boldsymbol{\eta}$$

or $\phi_a = v_a + \eta_a$ $\sum_{a=1}^N v_a^2 = \mathbf{v} \cdot \mathbf{v} = v^2$

Classically, \mathcal{H}_P is positive semi-definite & is minimum when $\boldsymbol{\phi}^2 = v^2$.

Ground state is therefore infinitely degenerate.

A simple choice is

$$v_a = v \delta_{aN} \quad \& \quad \eta_a | 0 \rangle = 0 \quad \forall a$$

Writing

$$\eta_N = \sigma \quad \& \quad \eta_a = \pi_a \quad \forall a = 1, \dots, N-1$$

we have

$$\phi_N = v + \sigma \quad \& \quad \phi_a = \pi_a \quad \forall a = 1, \dots, N-1$$

and

$$\langle 0 | \phi_a(x) | 0 \rangle = v \delta_{aN}$$

$$\phi^2 = \pi^2 + (v + \sigma)^2$$

$$\phi^2 - v^2 = \pi^2 + 2v\sigma + \sigma^2$$

$$(\phi^2 - v^2)^2 = 4v^2\sigma^2 + \dots$$

$$\rightarrow \mathcal{L} = \frac{1}{2} f \left(\partial_\mu \pi \cdot \partial^\mu \pi + \partial_\mu \sigma \cdot \partial^\mu \sigma - 2g v^2 \sigma^2 + \dots \right)$$

$$\therefore m_\sigma = \frac{\hbar \sqrt{2g}}{c} \quad \& \quad m_{\pi_a} = 0 \quad \forall a$$

The $\{\pi_a\}$ fields are Goldstone modes associated the spontaneous broken symmetry.

For $N=3$, the choice $\phi_i = S_i$ and

$$\langle 0 | \phi_1(x) | 0 \rangle = 0$$

$$\langle 0 | \phi_2(x) | 0 \rangle = 0$$

$$\langle 0 | \phi_3(x) | 0 \rangle = v$$

corresponds to spontaneous magnetization along the z-axis.

Consider the case $g \rightarrow \infty$ while v remains finite.

\mathcal{L} can be finite only if $\mathcal{H}_P = 0$, i.e.,

$$\phi^2 = v^2$$

so that

$$\mathcal{L} = \frac{1}{2} f \partial_\mu \phi \cdot \partial^\mu \phi$$

Ground state is infinitely degenerate.

Constraint $\phi^2 = v^2$ means only $N-1$ field are independent.

Choosing π as the independent fields,

$$\phi_N = \sqrt{v^2 - \pi^2} \quad (\text{massive } \sigma \text{ boson eliminated})$$

Since π transform nonlinearly under the $O(N)$ transformation, this is called non-linear sigma model.