

10.4. Landau Gauge

Landau gauge:

$$\mathbf{A} = B(-y, 0, 0)$$

$$\begin{aligned} \therefore \mathbf{D} &= \left(\partial_x + i \frac{eB}{\hbar c} y, \partial_y \right) \\ &= \left(\partial_x + i \frac{e}{l_B^2} y, \partial_y \right) \end{aligned}$$

$$(l_B^2 = \frac{\hbar c}{|e| B})$$

$$\mathbf{v} = \left(\frac{\hbar}{Mi} \partial_x + e\omega_c y, \frac{\hbar}{Mi} \partial_y \right)$$

$$(\omega_c = \frac{|e| B}{Mc} = \frac{\hbar}{M l_B^2})$$

$$\therefore \frac{e}{\omega_c} \mathbf{v} = (-ie l_B^2 \partial_x + y, -ie l_B^2 \partial_y)$$

$$\begin{aligned} \rightarrow \mathbf{v}^2 &= -\frac{\hbar^2}{M^2} \left\{ \left(\partial_x + i \frac{e}{l_B^2} y \right)^2 + \partial_y^2 \right\} \\ &= -\frac{\hbar^2}{M^2} \left(\partial_x^2 + \partial_y^2 - \frac{1}{l_B^4} y^2 + 2i \frac{e}{l_B^2} y \partial_x \right) \end{aligned}$$

$$\therefore \frac{1}{\omega_c^2} \mathbf{v}^2 = -l_B^4 (\partial_x^2 + \partial_y^2) + y^2 - 2ie l_B^2 y \partial_x$$

$$\begin{aligned} \mathbf{R} &= \mathbf{r} - \frac{e}{\omega_c} \hat{\mathbf{z}} \times \mathbf{v} \\ &= \left(x + \frac{e}{\omega_c} v_2, y - \frac{e}{\omega_c} v_1 \right) \\ &= (x - ie l_B^2 \partial_y, ie l_B^2 \partial_x) \end{aligned}$$

$$\begin{aligned} \rightarrow \mathbf{R}^2 &= (x - ie l_B^2 \partial_y)^2 - l_B^4 \partial_x^2 \\ &= x^2 - l_B^4 (\partial_x^2 + \partial_y^2) - 2ie l_B^2 x \partial_y \\ &= x^2 - y^2 + \frac{1}{\omega_c^2} \mathbf{v}^2 - 2ie l_B^2 (x \partial_y - y \partial_x) \\ &= x^2 - y^2 + \frac{1}{\omega_c^2} \mathbf{v}^2 + 2e l_B^2 \frac{L_3}{\hbar} \end{aligned}$$

$$H = \frac{1}{2} M \mathbf{v}^2 = -\frac{\hbar^2}{2M} \left(\partial_x^2 + \partial_y^2 - \frac{1}{l_B^4} y^2 + 2i \frac{e}{l_B^2} y \partial_x \right)$$

Since $\frac{\partial H}{\partial x} = 0$, we have

$$H\Psi = E\Psi$$

$$\rightarrow \Psi(x, y) = e^{ikx} \psi(y)$$

$$\& -\frac{\hbar^2}{2M} \left(-k^2 + \partial_y^2 - \frac{1}{l_B^4} y^2 - 2 \frac{e}{l_B^2} k y \right) \psi = E \psi$$

$$\left\{ -\partial_y^2 + \frac{1}{l_B^4} (y + e l_B^2 k)^2 \right\} \psi = \frac{2ME}{\hbar^2} \psi$$

$$\mathbf{R} = (x - ie l_B^2 \partial_y, -e l_B^2 k) \equiv (X, Y)$$

$$\rightarrow \left\{ -\partial_y^2 + \frac{1}{l_B^4} (y - Y)^2 \right\} \psi = \frac{2ME}{\hbar^2} \psi$$

Note: In this form, X is an operator but Y is just a number.

In dimensionless form

$$\left\{ -(l_B \partial_y)^2 + \left(\frac{y - Y}{l_B} \right)^2 \right\} \psi = \frac{2E}{\hbar \omega_c} \psi$$

Let

$$a = \alpha \left(\frac{y - Y}{l_B} + l_B \partial_y \right) \quad \rightarrow \quad a^\dagger = \alpha^* \left(\frac{y - Y}{l_B} - l_B \partial_y \right)$$

$$\therefore [a, a^\dagger] = \alpha \alpha^* (-[y, \partial_y] + [\partial_y, y]) = 2 \alpha \alpha^* \equiv 1$$

$$\rightarrow a = \frac{1}{\sqrt{2}} \left(\frac{y - Y}{l_B} + l_B \partial_y \right) \quad a^\dagger = \frac{1}{\sqrt{2}} \left(\frac{y - Y}{l_B} - l_B \partial_y \right)$$

$$a a^\dagger = \frac{1}{2} \left\{ \left(\frac{y - Y}{l_B} \right)^2 - (l_B \partial_y)^2 - [y, \partial_y] \right\} = \frac{1}{2} \left\{ \left(\frac{y - Y}{l_B} \right)^2 - (l_B \partial_y)^2 + 1 \right\}$$

$$a^\dagger a = \frac{1}{2} \left\{ \left(\frac{y - Y}{l_B} \right)^2 - (l_B \partial_y)^2 + [y, \partial_y] \right\} = \frac{1}{2} \left\{ \left(\frac{y - Y}{l_B} \right)^2 - (l_B \partial_y)^2 - 1 \right\}$$

$$\therefore a a^\dagger + a^\dagger a = \frac{2E}{\hbar \omega_c}$$

$$\rightarrow E = \hbar \omega_c \left(a^\dagger a + \frac{1}{2} \right) \\ = \hbar \omega_c \left(n + \frac{1}{2} \right) \quad n = 0, 1, 2, \dots$$

which is the same as the symmetric gauge, as it must be.

Using

$$\partial_y e^{-\alpha y^2} = -2\alpha y e^{-\alpha y^2}$$

$$\partial_y^2 e^{-\alpha y^2} = (-2\alpha + 4\alpha^2 y^2) e^{-\alpha y^2}$$

we see that the solution to the ground state eq.

$$\left\{ -(l_B \partial_y)^2 + \left(\frac{y - Y}{l_B} \right)^2 \right\} \psi_0 = \psi_0$$

is

$$\alpha = \frac{1}{2l_B^2}$$

$$\& \quad \psi_0 = C \exp \left\{ -\frac{1}{2} \left(\frac{y - Y}{l_B} \right)^2 \right\}$$

$$\langle \psi_0 | \psi_0 \rangle = C^* C \int_{-\infty}^{\infty} dy \exp \left\{ -\left(\frac{y - Y}{l_B} \right)^2 \right\} = C^* C \sqrt{\pi} l_B = 1$$

$$\rightarrow \psi_0 = \frac{1}{\sqrt{\pi^{1/2} l_B}} \exp \left\{ -\frac{1}{2} \left(\frac{y - Y}{l_B} \right)^2 \right\}$$

$$\Psi_{k0}(r) = \frac{1}{\sqrt{\pi^{1/2} l_B}} e^{ikx} \exp \left\{ -\frac{1}{2} \left(\frac{y - Y}{l_B} \right)^2 \right\}$$

Note that

$$\begin{aligned}\langle k0 | k'0 \rangle &= \int d^2 r \Psi_{k0}^*(\mathbf{r}) \Psi_{k'0}(\mathbf{r}) \\ &= \int dx e^{i(-k+k')x} = 2\pi \delta(k-k')\end{aligned}$$

Higher Landau levels are given by

$$\begin{aligned}\langle \mathbf{r} | kn \rangle &= \Psi_{kn}(\mathbf{r}) = \left\langle \mathbf{r} \left| \frac{a^{+n}}{\sqrt{n!}} \right| k0 \right\rangle \\ &= \frac{1}{\sqrt{2^n n!}} \left(\frac{y-Y}{l_B} - l_B \partial_y \right)^n \Psi_{k0}(\mathbf{r}) \quad (Y = -e l_B^2 k)\end{aligned}$$

which describes an oscillator in the y direction whose center is moving freely along the x -axis.

Consider a system of dimensions $L_x \times L_y$.

Imposing the periodic boundary condition on the plane wave makes

$$k = \frac{2\pi}{L_x} m \quad m = 0, 1, 2, \dots$$

so that the smallest separation between allowable values is $\Delta k = \frac{2\pi}{L_x}$.

This in turn makes

$$\Delta Y = \left| -e l_B^2 \Delta k \right| = l_B^2 \frac{2\pi}{L_x}$$

Each oscillator thus runs within a strip parallel to the x -axis & of effective width ΔY . The area it occupies is

$$\Delta S = L_x \Delta Y = 2\pi l_B^2$$

which is the same as in the symmetric gauge.

The Noether current density is (see 10.3._SymmetricGauge.pdf)

$$\begin{aligned}\mathbf{J} &= i \frac{e\hbar}{2M} [(\mathbf{D}\psi)^+ \psi - \psi^+ \mathbf{D}\psi] \\ D_x \Psi_{kn}(\mathbf{r}) &= \left(\partial_x + i \frac{e}{l_B^2} y \right) e^{ikx} \psi_n(y) \\ &= i \left(k + \frac{e}{l_B^2} y \right) \Psi_{kn}(\mathbf{r}) \\ D_y \Psi_{kn}(\mathbf{r}) &= e^{ikx} \partial_y \psi_n(y)\end{aligned}$$

For $n=0$ & switching to box normalization for the plane wave,

$$\begin{aligned}\Psi_{k0}(\mathbf{r}) &= \frac{1}{\sqrt{\pi^{1/2} l_B}} \frac{e^{ikx}}{\sqrt{L_x}} \exp \left\{ -\frac{1}{2} \left(\frac{y-Y}{l_B} \right)^2 \right\} \\ \rightarrow \partial_y \psi_0 &= -\left(\frac{y-Y}{l_B} \right) \psi_0 \\ \therefore J_x &= i \frac{e\hbar}{2M} \left\{ -i \left(k + \frac{e}{l_B^2} y \right) - i \left(k + \frac{e}{l_B^2} y \right) \right\} \Psi_{k0}^* \Psi_{k0} \\ &= \frac{e\hbar}{M} \left(k + \frac{e}{l_B^2} y \right) \Psi_{k0}^* \Psi_{k0}\end{aligned}$$

$$= \frac{|e| \hbar}{M l_B^3 \sqrt{\pi} L_x} (-Y + y) \exp \left\{ - \left(\frac{y - Y}{l_B} \right)^2 \right\} \quad (Y = -e l_B^2 k)$$

$$\rightarrow \langle J_x \rangle = \int_0^{L_x} dx \int_{-\infty}^{\infty} dy J_x = 0$$

$$J_y = i \frac{e \hbar}{2M} \left\{ - \left(\frac{y - Y}{l_B} \right) + \left(\frac{y - Y}{l_B} \right) \right\} \Psi_{k_0}^* \Psi_{k_0} = 0$$

That the average (macroscopic) linear current vanishes in all directions is to be expected for cyclotronic motion.