

#### 4.E.4. Binomial Random Walk

Consider the 1-D random walk problem. During each time interval  $\tau$ , a walker must take a step of fixed length  $\Delta$  either to the left with probability  $q = \frac{1}{2}$ , or to the right with probability  $p = \frac{1}{2}$ . The problem is to find the probability distribution for the net displacement of the walker after  $N$  steps ( or at time  $N\tau$  ).

Let the displacement of the  $i^{\text{th}}$  step be represented by the stochastic variable  $X_i$  with realizations  $\pm\Delta$ . The corresponding probability density is

$$P_{X_i}(x_i) = p \delta(x_i - \Delta) + q \delta(x_i + \Delta) = \frac{1}{2} \delta(x_i - \Delta) + \frac{1}{2} \delta(x_i + \Delta)$$

(4.61a)

which gives the characteristic function

$$\begin{aligned} f_{X_i}(k) &= \frac{1}{2} \int_{-\infty}^{\infty} dx_i e^{ikx} [\delta(x_i - \Delta) + \delta(x_i + \Delta)] \\ &= \frac{1}{2} (e^{ik\Delta} + e^{-ik\Delta}) \\ &= \cos k\Delta \end{aligned}$$

(4.61b)

For the event of  $N$  consecutive steps, the net displacement is represented by the stochastic variable

$$Y^{(N)} = X_1 + \dots + X_N$$

Since  $\{X_j\}$  are statistically independent,

$$P_{Y^{(N)}}(y) = P_{X_1}(x_1) \dots P_{X_N}(x_N)$$

and the characteristic function is simply [ c.f. (4.41) ]

$$\begin{aligned} f_{Y^{(N)}}(k) &= \int_{-\infty}^{\infty} dx_1 \dots \int_{-\infty}^{\infty} dx_N e^{ik(x_1 + \dots + x_N)} P_{X_1}(x_1) \dots P_{X_N}(x_N) \\ &= f_{X_1}(k) \dots f_{X_N}(k) \\ &= (\cos k\Delta)^N \end{aligned}$$

(4.61c)

$$\begin{aligned} &= \left( 1 - \frac{1}{2} k^2 \Delta^2 + \dots \right)^N \\ &= 1 - \frac{1}{2} N k^2 \Delta^2 + \dots \end{aligned}$$

(4.61)

Using (4.17) to calculate the moments, we get

$$\begin{aligned} \langle y \rangle &= -i \left. \frac{\partial f_{Y^{(N)}}(k)}{\partial k} \right|_{k=0} = i N \Delta (\sin k\Delta) (\cos k\Delta)^{N-1} \Big|_{k=0} = 0 \\ \langle y^2 \rangle &= -i \left. \frac{\partial}{\partial k} \left[ i N \Delta (\sin k\Delta) (\cos k\Delta)^{N-1} \right] \right|_{k=0} \\ &= N \Delta \left[ \Delta (\cos k\Delta) (\cos k\Delta)^{N-1} + (N-1) \Delta (\sin k\Delta)^2 (\cos k\Delta)^{N-2} \right] \Big|_{k=0} \\ &= N \Delta^2 \end{aligned}$$

$$\rightarrow \text{Var}(y) = N \Delta^2 \quad \& \quad \sigma_{Y^{(N)}} = \sqrt{N} \Delta$$

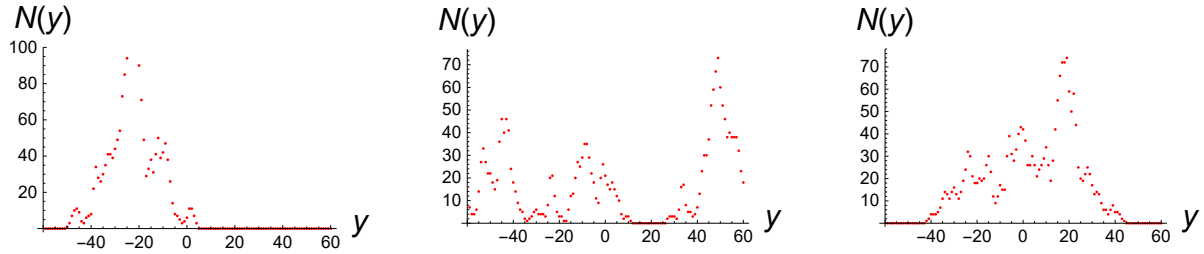


Fig.4.4. Results of three realizations of the random walk discussed above.

$N(y)$  is the number of times the walker reaches point  $y$ .

The walker is assumed to start at  $y=0$  and

$$N = 2000 \quad \Delta = 1 \quad p = q = \frac{1}{2}$$

Extension of the random walk to higher spatial dimensions is straightforward. After which, it can be used as a model for phenomena such as Brownian motion and diffusion. For such purposes, it would be helpful to obtain the (differential) equation of motion of the problem.

Setting  $t = N \tau$ , we can treat  $N$  as a time variable so that

$$Y^{(N)} = Y(t) \quad P_{Y^{(N)}}(y) = P_Y(y, t) \quad f_Y(k) = f_Y(k, t) \quad (4.62a)$$

In the continuum limit, i.e.,

$$N \rightarrow \infty \quad \tau \rightarrow 0 \quad \text{such that} \quad t = N \tau \neq 0$$

(4.62b)

$f_Y(k, t)$  becomes a continuous function of  $t$  so that we can derive a differential equation satisfied by it.

Thus,

$$\frac{\partial f_Y(k, t)}{\partial t} = \lim_{N \rightarrow \infty, \tau \rightarrow 0} \frac{f_{Y^{(N)}}[k, (N+1)\tau] - f_{Y^{(N)}}(k, N\tau)}{\tau}$$

(4.63)

$$= \lim_{N \rightarrow \infty, \tau \rightarrow 0} \frac{(\cos k \Delta - 1) f_{Y^{(N)}}(k, N\tau)}{\tau} \quad [ (4.61c) \text{ used. } ]$$

$$= \lim_{N \rightarrow \infty, \tau \rightarrow 0, \Delta \rightarrow 0} \frac{-(k\Delta)^2 f_{Y^{(N)}}(k, N\tau)}{2\tau}$$

(4.64a)

where we have applied the spatial continuum limit to set  $\Delta \rightarrow 0$ . In order to keep (4.64a) finite, we set

$$D = \lim_{\tau \rightarrow 0, \Delta \rightarrow 0} \frac{\Delta^2}{2\tau}$$

(4.64b)

so that (4.64a) becomes

$$\frac{\partial f_Y(k, t)}{\partial t} = -D k^2 f_Y(k, t)$$

(4.65)

Taking the inverse Fourier transform, we get the equation of motion we searched for:

$$\frac{\partial P_Y(y, t)}{\partial t} = D \frac{d^2 P_Y(y, t)}{dy^2}$$

(4.65a)

If we interpret  $P_Y(y, t)$  as the particle density, (4.65a) is just the 1-D **diffusion equation**, with  $D$  being the **diffusion coefficient**.

For the initial condition

$$f_Y(k, 0) = 1$$

the solution to (4.65) is easily verified to be

$$f_Y(k, t) = e^{-Dk^2 t}$$

(4.66)

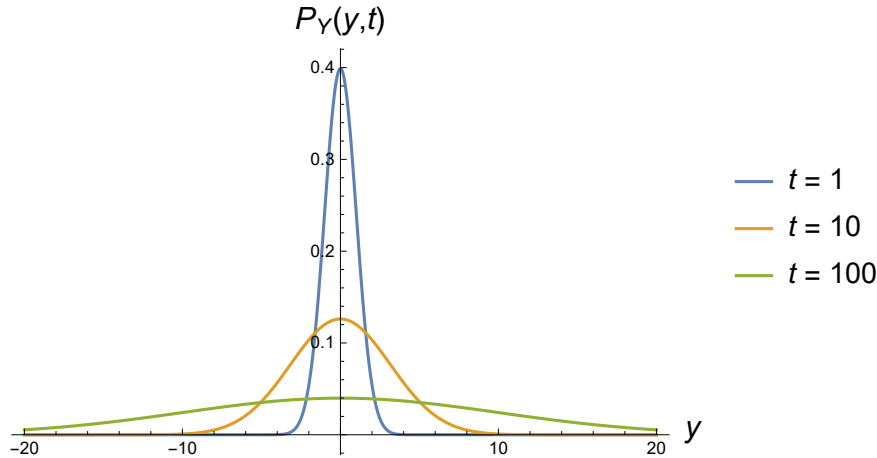
Taking the inverse Fourier transform, we get

$$\begin{aligned} P_Y(y, t) &= \int_{-\infty}^{\infty} \frac{dk}{2\pi} e^{-iky} e^{-Dk^2 t} \\ &= \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{y^2}{4Dt}\right) \end{aligned} \quad [\text{ See §Code }]$$

(4.67)

which is a Gaussian with  $\sigma_Y = \sqrt{2Dt}$ . Thus,  $P_Y(y, t)$  spreads out with time, as befits a diffusion.

(4.67) can be verified as a solution to (4.65a) [ see §Code ].



**Fig.4.5.** Spreading of  $P_Y(y, t)$  with time for  $D = \frac{1}{2}$ .

To emphasize the spatial continuum limit, we introduce the stochastic variable

$$Z^{(N)} = \frac{Y^{(N)}}{\Delta \sqrt{N}} \quad \& \quad z = \frac{y}{\Delta \sqrt{N}} = \frac{y}{\Delta \sqrt{t/\tau}} \xrightarrow{\Delta, \tau \rightarrow 0} \frac{y}{\sqrt{2Dt}} \quad [ (4.64b) \text{ used. } ]$$

(4.68a)

Using

$$P_{Z^{(N)}}(z) = \int_{-\infty}^{\infty} dy \delta\left(z - \frac{y}{\Delta \sqrt{N}}\right) P_Y(y)$$

(4.68b)

we have

$$\begin{aligned}
 f_{Z^{(N)}}(k) &= \int_{-\infty}^{\infty} dz e^{ikz} P_{Z^{(N)}}(z) \\
 &= \int_{-\infty}^{\infty} dz e^{ikz} \int_{-\infty}^{\infty} dy \delta\left(z - \frac{y}{\Delta \sqrt{N}}\right) P_{Y^{(N)}}(y) \\
 &= \int_{-\infty}^{\infty} dy e^{iky/\Delta \sqrt{N}} P_{Y^{(N)}}(y) \\
 &= f_{Y^{(N)}}\left(\frac{k}{\Delta \sqrt{N}}\right) \\
 &= \left[ \cos\left(\frac{k}{\Delta \sqrt{N}}\right) \right]^N \qquad \qquad \qquad [ (4.61c) \text{ used. } ]
 \end{aligned}$$

(4.68)

which is the same as (4.50) with  $p = q = \frac{1}{2}$ . Therefore, we can use (4.53) to write

$$f_Z(k) = \lim_{N \rightarrow \infty} f_{Z^{(N)}}(k) = e^{-k^2/2}$$

(4.69)

so that [ see (4.55) ]

$$P_Z(z) = \frac{1}{\sqrt{2\pi}} e^{-z^2/2}$$

(4.70)

Hence,

$$\begin{aligned}
 P_{Y^{(N)}}(y) &= \int_{-\infty}^{\infty} dz P_{Z^{(N)}}(z) \delta(y - \Delta \sqrt{N} z) \\
 &\approx \int_{-\infty}^{\infty} dz P_Z(z) \delta(y - \Delta \sqrt{N} z) \qquad \qquad \qquad \text{for } N \gg 1 \\
 &= \frac{1}{\Delta \sqrt{N}} \int_{-\infty}^{\infty} dz P_Z(z) \delta\left(z - \frac{y}{\Delta \sqrt{N}}\right) \\
 &= \frac{1}{\Delta \sqrt{2\pi N}} \exp\left(-\frac{y^2}{2\Delta^2 N}\right) \qquad \qquad \qquad [ (4.70) \text{ used. } ]
 \end{aligned}$$

(4.70)

$$\begin{aligned}
 \therefore P_Y(y, t) &= P_{Y^{(N)}}(y) \Big|_{N \Delta^2 = 2Dt} \qquad \qquad \qquad [ (4.62b) \ \& \ (4.64b) \ \text{combined.} ] \\
 &= \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{y^2}{4Dt}\right) \qquad \qquad \qquad (4.71)
 \end{aligned}$$

in agreement with (4.67).

## Code: Fig.4.4.

```

In[ ]:= ranWalk[Ns_, maxi_] := Module[ {Ny, y},
  Ny = Table[0, {i, -maxi, maxi}];
  y = 0;
  Do[
    y = y + 2 RandomInteger[] - 1;
    Ny[[y + maxi]] = Ny[[y + maxi]] + 1,
    {n, Ns}
  ];
  Table[ {i, Ny[[i + maxi]]}, {i, -maxi, maxi}
]

```

**Caution:** Errors occur if walker wanders beyond  $|y| = \text{maxi}$ .

```

In[ ]:= Ns = 2000; maxi = 60;
Ny = ranWalk[Ns, maxi];

In[ ]:= ListPlot[Ny, AxesOrigin -> {-maxi, 0},
  PlotStyle -> Red,
  AxesLabel -> {"y", "N(y)"}]

In[ ]:= Ny = ranWalk[Ns, maxi];
ListPlot[Ny, AxesOrigin -> {-maxi, 0},
  PlotStyle -> Red,
  AxesLabel -> {"y", "N(y)"}]

In[ ]:= Ny = ranWalk[Ns, maxi];
ListPlot[Ny, AxesOrigin -> {-maxi, 0},
  PlotStyle -> Red,
  AxesLabel -> {"y", "N(y)"}]

```

## Code

```

(* f_Y(y) *)
fY = e^{-d k^2 t}

Out[ ]:= e^{-d k^2 t}

(* P_Y(y) *)
PY = Assuming[ d > 0 && t > 0, \frac{1}{2 \pi} \int_{-\infty}^{\infty} e^{-i k y} fY dk]

Out[ ]:= \frac{e^{-\frac{y^2}{4 d t}}}{2 \sqrt{\pi} \sqrt{d t}}

(* Shows PY is solution to diffusion eq. *)
DtPY == d Dy,yPY // Simplify

Out[ ]:= True

```

```
In[*]:= (* Fig.4.5 *)  
ls = PY /. d ->  $\frac{1}{2}$  /. t -> {1, 10, 100};  
Plot[ls, {y, -20, 20},  
      PlotRange -> All,  
      AxesLabel -> {"y", "PY(y, t)"},  
      PlotLegends -> {"t = 1", "t = 10", "t = 100"}  
]
```