

12.B.1. Stability Conditions Near Equilibrium

Near equilibrium, we have [see (10.10.96)]

$$\mathcal{J}_i = -\sum_j L_{ij} \chi_j \quad (12.5)$$

where L_{ij} are transport coefficients satisfying [see §10.D.1.2]

$$L_{ij} = L_{ji} \quad [\text{Onsager's relation}] \quad (12.5a)$$

Near equilibrium, we are in the linear regime so that all L_{ij} are independent of the forces χ_k .

Putting (12.5) into (12.4-a) gives

$$T \sigma_s = \sum_{i,j} L_{ij} \chi_j \chi_i \geq 0 \quad (12.6)$$

which means the symmetric matrix $\mathbb{L} = \{L_{ij}\}$ is **positive semi-definite** (or non-negative definite).

Consider now the case of 2 forces so that (12.6) becomes

$$T \sigma_s = \sum_{i,j=1}^2 L_{ij} \chi_j \chi_i \geq 0 \quad (12.7)$$

Choosing χ_i as the independent variables, the conditions for extremum entropy production are [T is independent of χ_i even if $\chi_i = -\nabla_r T$]

$$\begin{aligned} 0 &= T \frac{\partial \sigma_s}{\partial \chi_1} = \sum_i L_{i1} \chi_i + \sum_j L_{1j} \chi_j = 2 \sum_i L_{i1} \chi_i && [(12.5a) \text{ used. }] \\ &= 2 (L_{11} \chi_1 + L_{21} \chi_2) = 2 (L_{11} \chi_1 + L_{12} \chi_2) \\ &= -2 \mathcal{J}_1 && [(12.5) \text{ used. }] \end{aligned} \quad (12.8)$$

and

$$\begin{aligned} 0 &= T \frac{\partial \sigma_s}{\partial \chi_2} = \sum_i L_{i2} \chi_i + \sum_j L_{2j} \chi_j = 2 \sum_i L_{i2} \chi_i && [(12.5a) \text{ used. }] \\ &= 2 (L_{12} \chi_1 + L_{22} \chi_2) = 2 (L_{21} \chi_1 + L_{22} \chi_2) \\ &= -2 \mathcal{J}_2 && [(12.5) \text{ used. }] \end{aligned} \quad (12.9)$$

Since \mathbb{L} is positive semi-definite,

$$\frac{\partial^2 \sigma_s}{\partial \chi_i \partial \chi_j} = \frac{L_{ij}}{T} \geq 0 \quad (12.9a)$$

Therefore, the extrema given by (12.8-9) are all minima corresponding to minimal entropy production.

Thus, minimum entropy production occurs when

$$\mathcal{J}_1 = \mathcal{J}_2 = 0$$

which, when substituted into (12.5), gives

$$\chi_1 = \chi_2 = 0$$

On the other hand, if we keep χ_1 constant, the conditions for minimum entropy production reduce to a single criterion

$$0 = T \frac{\partial \sigma_s}{\partial \chi_2} = -2 \mathcal{J}_2 \quad (12.10)$$

which turns (12.5) into

$$\begin{aligned}\mathcal{J}_1 &= -(L_{11} \chi_1 + L_{12} \chi_2) \\ 0 &= -(L_{21} \chi_1 + L_{22} \chi_2)\end{aligned}$$

with solutions

$$\begin{aligned}\chi_2 &= -\frac{L_{21}}{L_{22}} \chi_1 = \text{const} \\ \mathcal{J}_1 &= -\left(L_{11} \chi_1 - L_{12} \frac{L_{21}}{L_{22}} \chi_1\right) = -\frac{\det L}{L_{22}} \chi_1 = \text{const}\end{aligned}$$

so that the state of minimum entropy production is stationary.

These results can be easily generalized to the case of n independent forces $\{\chi_i; i = 1, \dots, n\}$. The entropy production (12.6) becomes

$$T \sigma_s = \sum_{i,j=1}^n L_{ij} \chi_j \chi_i \tag{12.11}$$

If we hold the first k forces $\{\chi_i; i = 1, \dots, k\}$ constant, the conditions for minimum entropy production are

$$0 = T \frac{\partial \sigma_s}{\partial \chi_i} = \sum_j L_{ji} \chi_j + \sum_j L_{ij} \chi_j = 2 \mathcal{J}_i \quad i = k+1, \dots, n \tag{12.12-3}$$

Thus, if the system is in a state of minimum entropy production, only fluxes conjugate to the forces being held constant exist.

Putting (12.13) into (12.5) gives

$$\mathcal{J}_i = -\sum_j L_{ij} \chi_j \quad i = 1, \dots, k \tag{12.13a}$$

$$0 = -\sum_j L_{ij} \chi_j \quad i = k+1, \dots, n \tag{12.13b}$$

(12.13b) can be solved for $\{\chi_i; i = k+1, \dots, n\}$ in terms of the constants L_{ij} and $\{\chi_i; i = 1, \dots, k\}$. This means $\{\chi_i; i = k+1, \dots, n\}$ are also constants in the state of minimum entropy production. By (12.13a), the nonvanishing fluxes $\{\mathcal{J}_i; i = 1, \dots, k\}$ are also constants. Such a state is called stationary to the k^{th} order.

Next, we consider the stability of a stationary state of the general (non-linear) entropy production.

As described in Appendix C.3, a stationary state at point $\bar{\mathbf{y}}$ in phase space is stable if there exists a **Liapounov function** $V(\mathbf{y})$ in a neighborhood \mathcal{N} of $\bar{\mathbf{y}}$ such that for all $\mathbf{y} \in \mathcal{N}$,

1. $V(\mathbf{y}) \geq 0$ with $V=0$ only at $\mathbf{y} = \bar{\mathbf{y}}$ (12.13c)

2. $\frac{dV}{dt} \leq 0$ (12.13d)

Consider again a system of n independent forces $\{\chi_i; i = 1, \dots, n\}$ with the first k forces $\{\chi_i; i = 1, \dots, k\}$ being held constant. Let the properties of the stationary state be denoted by a superscript 0. The entropy production near the stationary state can be expanded as a Taylor series

$$\begin{aligned}
\sigma_s(\chi_{k+1}, \dots, \chi_n) &= \sigma_s(\chi_{k+1}^0, \dots, \chi_n^0) + \sum_{i=k+1}^n \left(\frac{\partial \sigma_s}{\partial \chi_i} \right)^0 \delta \chi_i \quad [\delta \chi_i = \chi_i - \chi_i^0] \\
&\quad + \frac{1}{2} \sum_{i,j=k+1}^n \left(\frac{\partial^2 \sigma_s}{\partial \chi_i \partial \chi_j} \right)^0 \delta \chi_i \delta \chi_j + \dots \\
&= \sigma_s(\chi_{k+1}^0, \dots, \chi_n^0) - \frac{1}{2T} \sum_{i,j=k+1}^n L_{ij} \delta \chi_i \delta \chi_j + \dots \quad (12.14)
\end{aligned}$$

where, from (12.9a) was used.

The quantity

$$\begin{aligned}
\Delta P &= \int d^3 r T [\sigma_s(\chi_{k+1}, \dots, \chi_n) - \sigma_s(\chi_{k+1}^0, \dots, \chi_n^0)] \\
&= \frac{1}{2} \int d^3 r \sum_{i,j=k+1}^n L_{ij} \delta \chi_i \delta \chi_j \quad (12.15) \\
&\geq 0 \quad [(12.6) \text{ used. }]
\end{aligned}$$

is called the **excess entropy production**. Taking the time derivative gives

$$\begin{aligned}
\frac{d\Delta P}{dt} &= \frac{1}{2} \int d^3 r \sum_{i,j=k+1}^n L_{ij} \left(\frac{d\delta \chi_i}{dt} \delta \chi_j + \delta \chi_i \frac{d\delta \chi_j}{dt} \right) \\
&= -\frac{1}{2} \int d^3 r \left(\sum_{j=k+1}^n \frac{d\delta \chi_j}{dt} \delta \mathcal{J}_j + \sum_{i=k+1}^n \delta \mathcal{J}_i \frac{d\delta \chi_i}{dt} \right) \quad [(12.5) \text{ used. }] \\
&= -\int d^3 r \sum_{j=k+1}^n \frac{d\delta \chi_j}{dt} \delta \mathcal{J}_j \quad (12.16a)
\end{aligned}$$

From (10.79) of §10.D.1, we have

$$\begin{aligned}
\chi &= T \mathbf{g} \cdot \alpha \\
\rightarrow \delta \chi &= T \mathbf{g} \cdot \delta \alpha \\
\frac{d\delta \chi}{dt} &= T \mathbf{g} \cdot \frac{d\delta \alpha}{dt} = T \mathbf{g} \cdot \delta \mathcal{J} \quad [(10.80) \text{ used. }] \\
\therefore \frac{d\delta \chi_j}{dt} &= T \sum_i g_{ji} \delta \mathcal{J}_i
\end{aligned}$$

(12.16a) thus becomes

$$\begin{aligned}
\frac{d\Delta P}{dt} &= -T \int d^3 r \sum_{i,j=k+1}^n g_{ji} \delta \mathcal{J}_i \delta \mathcal{J}_j \\
&\leq 0 \quad [\mathbf{g} \text{ is positive definite. }] \quad (12.16)
\end{aligned}$$

ΔP is therefore a Lyapunov function and the stationary state is stable in the linear regime.

In the nonlinear regime, (12.5) no longer holds so that $\frac{d\Delta P}{dt}$ cannot be put into the form (12.16), i.e.,

ΔP may not be a Lyapunov function and the stability of the stationary state is not guaranteed. Phase transition far from equilibrium is then a possibility.