

Read Reichl's introduction.

Tables & proofs for vector calculus formulas can be found in the standard textbooks G.Arken's "Mathematical Methods for Physicists" and J.D.Jackson's "Classical Electrodynamics".

SI0.G.I. Fluid Flow Around the Brownian Particle

Consider the linearized hydrodynamic equations [see (10.36-7) of §10.C.1 with $F = 0$]

$$\begin{aligned} \frac{\partial \Delta \rho}{\partial t} + \rho_0 \nabla_r \cdot \mathbf{v} &= 0 \\ \rho_0 \frac{\partial \mathbf{v}}{\partial t} &= -\nabla_r \Delta P + \left(\zeta + \frac{1}{3} \eta \right) \nabla_r (\nabla_r \cdot \mathbf{v}) + \eta \nabla_r^2 \mathbf{v} \end{aligned}$$

Taking the Fourier transform on t gives

$$(10.353) \quad -i \omega \rho_0 \mathbf{v}_\omega(\mathbf{r}) + \rho_0 \nabla_r \cdot \mathbf{v}_\omega(\mathbf{r}) = 0$$

$$(10.354a) \quad -i \omega \rho_0 \mathbf{v}_\omega(\mathbf{r}) = -\nabla_r P_\omega(\mathbf{r}) + \left(\zeta + \frac{1}{3} \eta \right) \nabla_r (\nabla_r \cdot \mathbf{v}_\omega(\mathbf{r})) + \eta \nabla_r^2 \mathbf{v}_\omega(\mathbf{r})$$

Using

$$\begin{aligned} \nabla_r \times (\nabla_r \times \mathbf{v}) &= \epsilon_{ijk} \partial_j (\epsilon_{klm} \partial_l v_m) \\ &= (\delta_{ij} \delta_{jm} - \delta_{im} \delta_{jl}) \partial_j \partial_l v_m \\ &= \partial_j \partial_i v_j - \partial_j \partial_j v_i \\ &= \nabla_r (\nabla_r \cdot \mathbf{v}) - \nabla_r^2 \mathbf{v} \end{aligned} \quad (10.354b)$$

to eliminate $\nabla_r^2 \mathbf{v}_\omega(\mathbf{r})$, (10.354a) becomes

$$(10.354) \quad -i \omega \rho_0 \mathbf{v}_\omega(\mathbf{r}) = -\nabla_r P_\omega(\mathbf{r}) + \left(\zeta + \frac{4}{3} \eta \right) \nabla_r (\nabla_r \cdot \mathbf{v}_\omega(\mathbf{r})) - \eta \nabla_r \times (\nabla_r \times \mathbf{v}_\omega(\mathbf{r}))$$

Consider a spherical Brownian particle of radius R moving through the fluid with velocity $\mathbf{u}(t) = u(t) \hat{\mathbf{z}}$.

Let the surface of the Brownian particle be highly sticky so that the velocity $\mathbf{v}(\mathbf{r}, t)$ of the fluid is equal to that of the Brownian particle everywhere on its surface.

The total force on the Brownian particle is

$$(10.355) \quad \mathbf{F} = \oint_S d\mathbf{S} \cdot \mathbf{P} = \oint_S dS \hat{\mathbf{r}} \cdot \mathbf{P}$$

where S is the surface of the Brownian particle and

$$\mathbf{P} = P \mathbb{I} + \mathbf{\Pi}$$

is the pressure tensor of the fluid [see §10.B.1].

For an incompressible fluid,

$$\nabla_r \cdot \mathbf{v}(\mathbf{r}, t) = 0 \quad \rightarrow \quad \nabla_r \cdot \mathbf{v}_\omega(\mathbf{r}) = 0$$

and (10.353) & (10.354) simplify to

$$(10.356a) \quad -i \omega \rho_0 \mathbf{v}_\omega(\mathbf{r}) = 0$$

$$(10.356) \quad -i \omega \rho_0 \mathbf{v}_\omega(\mathbf{r}) = -\nabla_r P_\omega(\mathbf{r}) - \eta \nabla_r \times (\nabla_r \times \mathbf{v}_\omega(\mathbf{r}))$$

Using

$$\nabla_r \times \nabla_r f = 0 \quad \forall f \quad (10.356b)$$

we can write (10.356) as

$$\begin{aligned} -i \omega \rho_0 \nabla_r \times \mathbf{v}_\omega(\mathbf{r}) &= -\eta \nabla_r \times \left[\nabla_r \times \left(\nabla_r \times \mathbf{v}_\omega(\mathbf{r}) \right) \right] \\ &= -\eta \nabla_r \times \left[\nabla_r \left(\nabla_r \cdot \mathbf{v}_\omega(\mathbf{r}) \right) - \nabla_r^2 \mathbf{v}_\omega(\mathbf{r}) \right] \quad [(10.354b) \text{ used. }] \\ &= \eta \nabla_r \times \left[\nabla_r^2 \mathbf{v}_\omega(\mathbf{r}) \right] \quad [(10.356b) \text{ used. }] \\ &= \eta \epsilon_{ijk} \partial_j (\partial_m \partial_m v_{\omega k}) \\ &= \eta \partial_m \partial_m \epsilon_{ijk} \partial_j v_{\omega k} \\ &= \eta \nabla_r^2 \left[\nabla_r \times \mathbf{v}_\omega(\mathbf{r}) \right] \end{aligned} \quad (10.358)$$

Now, the boundary condition at the surface of the Brownian particle means that the flow is symmetric about $\hat{\mathbf{u}} = \hat{\mathbf{z}}$, i.e., it is independent of ϕ . Setting

$$\boldsymbol{\xi} = \mathbf{r} - \mathbf{r}_c \quad \xi = |\boldsymbol{\xi}|$$

where

$\mathbf{r}_c(t)$ = position of the center of the Brownian particle at time t

so that $(\hat{\boldsymbol{\xi}}, \hat{\boldsymbol{\theta}}, \hat{\boldsymbol{\phi}})$ form a spherical coordinate basis, we can use

$$\hat{\boldsymbol{\xi}} \times (\hat{\boldsymbol{\xi}} \times \hat{\mathbf{u}}) = \hat{\boldsymbol{\theta}} \cos \theta$$

to write

$$\begin{aligned} \mathbf{v}(\mathbf{r}, t) &= \mathbf{u}(t) A(\xi, \theta) + \hat{\boldsymbol{\xi}} \times \left[\hat{\boldsymbol{\xi}} \times \mathbf{u}(t) \right] B(\xi, \theta) \\ \rightarrow \mathbf{v}_\omega(\mathbf{r}) &= \mathbf{u}_\omega A(\xi, \theta) + \hat{\boldsymbol{\xi}} \times \left(\hat{\boldsymbol{\xi}} \times \mathbf{u}_\omega \right) B(\xi, \theta) \end{aligned} \quad (10.357a)$$

Thus, \mathbf{v}_ω is always in the $(\hat{\mathbf{z}}, \hat{\boldsymbol{\xi}})$ plane & hence independent of ϕ , both in magnitude & direction.

Alternatively, consider

$$\begin{aligned} \nabla_r \times [\nabla_r \times (\mathbf{u}_\omega g)] &= \nabla_\xi \times [\nabla_\xi \times (\mathbf{u}_\omega g)] \\ &= \nabla_\xi [\nabla_\xi \cdot (\mathbf{u}_\omega g)] - \nabla_\xi^2 (\mathbf{u}_\omega g) \\ &= \nabla_\xi (\mathbf{u}_\omega \cdot \nabla_\xi g) - \mathbf{u}_\omega \nabla_\xi^2 g \end{aligned}$$

If we set $g = g(\xi)$, we get

$$\begin{aligned} \nabla_\xi \times \left\{ \nabla_\xi \times \left[\mathbf{u}_\omega g(\xi) \right] \right\} &= \nabla_\xi \left(u_\omega \cos \theta \frac{dg}{d\xi} \right) - \mathbf{u}_\omega \nabla_\xi^2 g \\ &= -\hat{\boldsymbol{\theta}} \frac{u_\omega \sin \theta}{\xi} \frac{dg}{d\xi} + \hat{\boldsymbol{\xi}} u_\omega \cos \theta \frac{d^2 g}{d\xi^2} - \mathbf{u}_\omega \nabla_\xi^2 g \end{aligned} \quad (10.357b)$$

where we have used

$$\nabla_\xi \psi(\xi, \theta, \phi) = \hat{\boldsymbol{\xi}} \frac{\partial \psi}{\partial \xi} + \hat{\boldsymbol{\theta}} \frac{1}{\xi} \frac{\partial \psi}{\partial \theta} + \hat{\boldsymbol{\phi}} \frac{1}{\xi \sin \theta} \frac{\partial \psi}{\partial \phi}$$

Since $\hat{\mathbf{z}}, \hat{\boldsymbol{\xi}}, \hat{\boldsymbol{\theta}}$ are in the same plane, we can replace (10.357a) with the more efficient form

$$\mathbf{v}_\omega(\mathbf{r}) = \mathbf{v}_\omega(\mathbf{r}_c + \boldsymbol{\xi}) = \nabla_\xi \times \left\{ \nabla_\xi \times \left[\mathbf{u}_\omega g(\xi) \right] \right\} \quad (10.357)$$

Furthermore, using

$$\hat{z} = \hat{\xi} \cos \theta - \hat{\theta} \sin \theta \quad \nabla_{\xi}^2 g(\xi) = \frac{1}{\xi^2} \frac{d}{d\xi} \xi^2 \frac{dg}{d\xi} = \frac{d^2 g}{d\xi^2} + \frac{2}{\xi} \frac{dg}{d\xi}$$

we have

$$\mathbf{v}_{\omega}(r) = \hat{\theta} u_{\omega} \sin \theta \left(\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) - \hat{\xi} u_{\omega} \cos \theta \left(\frac{2}{\xi} \frac{dg}{d\xi} \right) \quad (10.365)$$

which is the representation of $\mathbf{v}_{\omega}(r)$ in spherical coordinates.

Using

$$\nabla_{\xi} \times \mathbf{A} = \frac{1}{\xi^2 \sin \theta} \begin{vmatrix} \hat{\xi} & \xi \hat{\theta} & \xi \sin \theta \hat{\phi} \\ \partial_{\xi} & \partial_{\theta} & \partial_{\phi} \\ A_{\xi} & \xi A_{\theta} & \xi \sin \theta A_{\phi} \end{vmatrix}$$

we have

$$\begin{aligned} \nabla_{\xi} \times [\hat{\theta} \sin \theta f(\xi)] &= \frac{1}{\xi^2 \sin \theta} \begin{vmatrix} \hat{\xi} & \xi \hat{\theta} & \xi \sin \theta \hat{\phi} \\ \partial_{\xi} & \partial_{\theta} & \partial_{\phi} \\ 0 & \xi \sin \theta f(\xi) & 0 \end{vmatrix} \\ &= \hat{\phi} \frac{\sin \theta}{\xi} \frac{d}{d\xi} [\xi f(\xi)] = \hat{\phi} \frac{\sin \theta}{\xi} \left(f + \xi \frac{df}{d\xi} \right) \\ \nabla_{\xi} \times [\hat{\xi} \cos \theta f(\xi)] &= \frac{1}{\xi^2 \sin \theta} \begin{vmatrix} \hat{\xi} & \xi \hat{\theta} & \xi \sin \theta \hat{\phi} \\ \partial_{\xi} & \partial_{\theta} & \partial_{\phi} \\ \cos \theta f(\xi) & 0 & 0 \end{vmatrix} = \hat{\phi} \sin \theta \frac{f}{\xi} \end{aligned}$$

so that (10.365) gives

$$\begin{aligned} \nabla_{\xi} \times \mathbf{v}_{\omega}(r) &= \hat{\phi} \frac{u_{\omega} \sin \theta}{\xi} \left[\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} + \xi \frac{d}{d\xi} \left(\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) - \frac{2}{\xi} \frac{dg}{d\xi} \right] \\ &= \hat{\phi} \frac{u_{\omega} \sin \theta}{\xi} \left[-\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} + \xi \left(-\frac{1}{\xi^2} \frac{dg}{d\xi} + \frac{1}{\xi} \frac{d^2 g}{d\xi^2} + \frac{d^3 g}{d\xi^3} \right) \right] \\ &= \hat{\phi} \frac{u_{\omega} \sin \theta}{\xi} \left(-\frac{2}{\xi} \frac{dg}{d\xi} + 2 \frac{d^2 g}{d\xi^2} + \xi \frac{d^3 g}{d\xi^3} \right) \\ &= \hat{\phi} u_{\omega} \sin \theta \frac{d}{d\xi} \nabla_{\xi}^2 g \end{aligned}$$

(10.359)

Using

$$\begin{aligned} \hat{\phi} &= -\sin \phi \hat{x} + \cos \phi \hat{y} \\ \nabla_{\xi}^2 \psi(\xi, \theta, \phi) &= \frac{1}{\xi^2} \frac{\partial}{\partial \xi} \xi^2 \frac{\partial \psi}{\partial \xi} + \frac{1}{\xi^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial \psi}{\partial \theta} + \frac{1}{\xi^2 \sin^2 \theta} \frac{\partial^2 \psi}{\partial \phi^2} \end{aligned}$$

we have

$$\begin{aligned} \nabla_{\xi}^2 \hat{\phi} &= -\hat{x} \nabla_{\xi}^2 \sin \phi + \hat{y} \nabla_{\xi}^2 \cos \phi \\ &= \frac{1}{\xi^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} (-\sin \phi \hat{x} + \cos \phi \hat{y}) \\ &= \frac{1}{\xi^2 \sin^2 \theta} (\sin \phi \hat{x} - \cos \phi \hat{y}) \end{aligned}$$

$$= -\frac{1}{\xi^2 \sin^2 \theta} \hat{\phi}$$

Also,

$$\begin{aligned} \nabla_{\xi}^2 [\sin \theta f(\xi)] &= \sin \theta \nabla_{\xi}^2 f(\xi) + \frac{f(\xi)}{\xi^2 \sin \theta} \frac{d}{d \theta} \left(\sin \theta \frac{d \sin \theta}{d \theta} \right) \\ &= \sin \theta \nabla_{\xi}^2 f(\xi) + \frac{f(\xi) \cos 2\theta}{\xi^2 \sin \theta} \end{aligned}$$

$$\begin{aligned} \rightarrow \nabla_{\xi}^2 (\hat{\phi} \sin \theta f(\xi)) &= -\frac{1}{\xi^2 \sin^2 \theta} \hat{\phi} \sin \theta f(\xi) + \hat{\phi} \left(\sin \theta \nabla_{\xi}^2 f(\xi) + \frac{f(\xi) \cos 2\theta}{\xi^2 \sin \theta} \right) \\ &= \left(\frac{\cos 2\theta - 1}{\xi^2 \sin \theta} f(\xi) + \sin \theta \nabla_{\xi}^2 f(\xi) \right) \hat{\phi} \\ &= \sin \theta \left(-\frac{2}{\xi^2} f(\xi) + \nabla_{\xi}^2 f(\xi) \right) \hat{\phi} \end{aligned}$$

(10.359) then gives

$$\nabla_{\xi}^2 [\nabla_{\xi} \times \mathbf{v}_{\omega}(r)] = \hat{\phi} u_{\omega} \sin \theta \left(-\frac{2}{\xi^2} \frac{d}{d \xi} \nabla_{\xi}^2 g + \nabla_{\xi}^2 \frac{d}{d \xi} \nabla_{\xi}^2 g \right)$$

(10.359a)

Putting (10.359-a) into (10.358) gives

$$-i \omega \rho_0 \hat{\phi} u_{\omega} \sin \theta \frac{d}{d \xi} \nabla_{\xi}^2 g = \eta \hat{\phi} u_{\omega} \sin \theta \left(-\frac{2}{\xi^2} \frac{d}{d \xi} \nabla_{\xi}^2 g + \nabla_{\xi}^2 \frac{d}{d \xi} \nabla_{\xi}^2 g \right)$$

$$\rightarrow -i \omega \rho_0 \frac{d}{d \xi} \nabla_{\xi}^2 g = \eta \left(-\frac{2}{\xi^2} \frac{d}{d \xi} \nabla_{\xi}^2 g + \nabla_{\xi}^2 \frac{d}{d \xi} \nabla_{\xi}^2 g \right)$$

(10.360)

Using

$$\begin{aligned} \nabla_{\xi}^2 \frac{d}{d \xi} &= \left(\frac{d^2}{d \xi^2} + \frac{2}{\xi} \frac{d}{d \xi} \right) \frac{d}{d \xi} = \frac{d^3}{d \xi^3} + \frac{2}{\xi} \frac{d^2}{d \xi^2} = \frac{d^3}{d \xi^3} + \frac{d}{d \xi} \left(\frac{2}{\xi} \frac{d}{d \xi} \right) + \frac{2}{\xi^2} \frac{d}{d \xi} \\ &= \frac{d}{d \xi} \nabla_{\xi}^2 + \frac{2}{\xi^2} \frac{d}{d \xi} \end{aligned}$$

(10.360) becomes

$$\begin{aligned} -i \omega \rho_0 \frac{d}{d \xi} \nabla_{\xi}^2 g &= \eta \left[-\frac{2}{\xi^2} \frac{d}{d \xi} \nabla_{\xi}^2 g + \left(\frac{d}{d \xi} \nabla_{\xi}^2 + \frac{2}{\xi^2} \frac{d}{d \xi} \right) \nabla_{\xi}^2 g \right] \\ &= \eta \frac{d}{d \xi} \nabla_{\xi}^4 g \end{aligned}$$

(10.360a)

Setting

$$k^2 = \frac{i \omega \rho_0}{\eta} \rightarrow k = \sqrt{\frac{\omega \rho_0}{\eta}} e^{i\pi/4} = \sqrt{\frac{\omega \rho_0}{2 \eta}} (1 + i)$$

(10.360b)

we get

$$\frac{d}{d\xi} \left[\nabla_{\xi}^4 g + k^2 \nabla_{\xi}^2 g \right] = 0 \quad (10.361)$$

$$\rightarrow \nabla_{\xi}^4 g + k^2 \nabla_{\xi}^2 g = C \quad C = \text{const} \quad (10.362)$$

Now, far away from the Brownian particle, the fluid is undisturbed so that

$$\begin{aligned} \mathbf{v}(\mathbf{r}, t) &= 0 & \text{as } \xi \rightarrow \infty & \quad \forall t \\ \rightarrow \mathbf{v}_{\omega}(\mathbf{r}) &= 0 & \text{as } \xi \rightarrow \infty & \\ \rightarrow \frac{d^n}{d\xi^n} \nabla_{\xi}^2 g &= 0 & \text{as } \xi \rightarrow \infty & \quad \forall n \\ \rightarrow C &= 0 \end{aligned}$$

Thus, (10.362) becomes

$$\nabla_{\xi}^2 (\nabla_{\xi}^2 g) + k^2 \nabla_{\xi}^2 g = 0 \quad (10.362a)$$

with solution that vanishes as $\xi \rightarrow \infty$ given by

$$\nabla_{\xi}^2 g = \frac{c_1}{\xi} e^{ik\xi} \quad [\text{see §Code}] \quad (10.363)$$

(10.363) can be written as

$$\begin{aligned} \frac{d}{d\xi} \xi^2 \frac{dg}{d\xi} &= c_1 \xi e^{ik\xi} \\ \rightarrow \xi^2 \frac{dg}{d\xi} &= c_1 \int d\xi \xi e^{ik\xi} + c_2 \\ &= c_1 e^{ik\xi} \left(\frac{1}{k^2} + \frac{\xi}{ik} \right) + c_2 \quad [\text{see §Code}] \\ \therefore \frac{dg}{d\xi} &= \frac{1}{\xi^2} \left[c_1 e^{ik\xi} \left(\frac{1}{k^2} + \frac{\xi}{ik} \right) + c_2 \right] \end{aligned} \quad (10.364)$$

To impose the boundary condition at $\xi = R$, we need to express $\mathbf{v}_{\omega}(\mathbf{r})$ in the cylindrical coordinate basis $(\hat{\rho}, \hat{\phi}, \hat{z})$. Putting

$$\hat{\xi} = \hat{\rho} \sin \theta + \hat{z} \cos \theta \quad \hat{\theta} = \hat{\rho} \cos \theta - \hat{z} \sin \theta$$

into (10.365) gives

$$\begin{aligned} \mathbf{v}_{\omega}(\mathbf{r}) &= (\hat{\rho} \cos \theta - \hat{z} \sin \theta) u_{\omega} \sin \theta \left(\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) - (\hat{\rho} \sin \theta + \hat{z} \cos \theta) u_{\omega} \cos \theta \left(\frac{2}{\xi} \frac{dg}{d\xi} \right) \\ &= \hat{\rho} u_{\omega} \left[\cos \theta \sin \theta \left(\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) - \sin \theta \cos \theta \left(\frac{2}{\xi} \frac{dg}{d\xi} \right) \right] \\ &\quad - \hat{z} u_{\omega} \left[\sin^2 \theta \left(\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) + \cos^2 \theta \left(\frac{2}{\xi} \frac{dg}{d\xi} \right) \right] \\ &= \hat{\rho} u_{\omega} \sin \theta \cos \theta \left(-\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) - \hat{z} u_{\omega} \left[\sin^2 \theta \left(-\frac{1}{\xi} \frac{dg}{d\xi} + \frac{d^2 g}{d\xi^2} \right) + \frac{2}{\xi} \frac{dg}{d\xi} \right] \end{aligned}$$

$$= \hat{\rho} u_\omega \sin\theta \cos\theta \left(-\frac{3}{\xi} \frac{dg}{d\xi} + \nabla_\xi^2 g \right) - \hat{z} u_\omega \left[\sin^2\theta \left(-\frac{3}{\xi} \frac{dg}{d\xi} + \nabla_\xi^2 g \right) + \frac{2}{\xi} \frac{dg}{d\xi} \right] \quad (10.365a)$$

The boundary condition

$$\mathbf{v}_\omega(r) \Big|_{\xi=R} = \hat{z} u_\omega \quad \forall \theta$$

then requires

$$\left(-\frac{3}{\xi} \frac{dg}{d\xi} + \nabla_\xi^2 g \right) \Big|_{\xi=R} = 0 \quad \frac{2}{\xi} \frac{dg}{d\xi} \Big|_{\xi=R} = -1 \quad (10.365b)$$

$$\rightarrow \nabla_\xi^2 g \Big|_{\xi=R} = -\frac{3}{2} \quad (10.365c)$$

Putting these into (10.363) gives

$$\begin{aligned} -\frac{3}{2} &= \frac{c_1}{R} e^{ikR} \\ \rightarrow c_1 &= -\frac{3R}{2} e^{-ikR} \end{aligned} \quad (10.366)$$

while (10.364) gives

$$\begin{aligned} -\frac{R}{2} &= \frac{1}{R^2} \left[c_1 e^{ikR} \left(\frac{1}{k^2} + \frac{R}{ik} \right) + c_2 \right] \\ &= \frac{1}{R^2} \left[-\frac{3R}{2} \left(\frac{1}{k^2} + \frac{R}{ik} \right) + c_2 \right] \quad [(10.366) \text{ used. }] \\ \rightarrow c_2 &= -\frac{R^3}{2} + \frac{3R}{2} \left(\frac{1}{k^2} + \frac{R}{ik} \right) \\ &= \frac{R^3}{2} \left(-1 + \frac{3}{ikR} + \frac{3}{k^2 R^2} \right) \end{aligned} \quad (10.366a)$$

(10.363, 4 & 5) become

$$\nabla_\xi^2 g = -\frac{3R}{2\xi} e^{ik(\xi-R)} \quad (10.366b)$$

$$\frac{dg}{d\xi} = \frac{1}{\xi^2} \left[-\frac{3R}{2} e^{ik(\xi-R)} \left(\frac{1}{k^2} + \frac{\xi}{ik} \right) + \frac{R^3}{2} \left(-1 + \frac{3}{ikR} + \frac{3}{k^2 R^2} \right) \right] \quad (10.366c)$$

$$\begin{aligned} \mathbf{v}_\omega(r) &= \hat{\theta} u_\omega \sin\theta \left(-\frac{1}{\xi} \frac{dg}{d\xi} + \nabla_\xi^2 g \right) - \hat{\xi} u_\omega \cos\theta \left(\frac{2}{\xi} \frac{dg}{d\xi} \right) \\ &= \hat{\theta} \frac{u_\omega \sin\theta}{\xi^3} \left[\frac{3R}{2} e^{ik(\xi-R)} \left(\frac{1}{k^2} + \frac{\xi}{ik} - \xi^2 \right) - \frac{R^3}{2} \left(-1 + \frac{3}{ikR} + \frac{3}{k^2 R^2} \right) \right] \\ &\quad - \hat{\xi} \frac{2 u_\omega \cos\theta}{\xi^3} \left[-\frac{3R}{2} e^{ik(\xi-R)} \left(\frac{1}{k^2} + \frac{\xi}{ik} \right) + \frac{R^3}{2} \left(-1 + \frac{3}{ikR} + \frac{3}{k^2 R^2} \right) \right] \end{aligned} \quad (10.366d)$$

$$\rightarrow \mathbf{v}_\omega(r) \Big|_{\xi=R} = -\hat{\theta} u_\omega \sin\theta + \hat{\xi} u_\omega \cos\theta = u_\omega \hat{z}$$

as expected.

Code

```
DSolve[f''[\xi] + \frac{2}{\xi} f'[\xi] + k^2 f[\xi] == 0, f, \xi]
```

```
{f -> Function[\xi, \frac{e^{-\sqrt{-k^2} \xi} C[1]}{\xi} + \frac{e^{\sqrt{-k^2} \xi} C[2]}{2 \sqrt{-k^2} \xi}]}
```

$$\int e^{i k \xi} \xi \, d\xi$$

$$e^{i k \xi} \left(\frac{1}{k^2} - \frac{i \xi}{k} \right)$$