

S.12.A.1. Fluctuations in the Rayleigh-Benard System

As shown in Ex.12.3, the first bifurcation for smooth boundaries occurs at

$$n = 1 \quad \mathcal{R}_c = \frac{27}{4} \pi^4 \quad q_c = \left(\sqrt{k_x^2 + k_y^2} \right)_c = \frac{\pi}{\sqrt{2} d} \quad (12.111a)$$

so that [see (2)]

$$\tilde{v}_z(z) = A \sin \frac{\pi z}{d} \quad k_{zc} = \frac{\pi}{d}$$

and [see (12.102) with $\omega = 0$ for persistent modes]

$$v_z(\mathbf{r}, t) = A \sin \frac{\pi z}{d} e^{i(k_x x + k_y y)} \quad (12.111)$$

Caution: the definition $\mathbf{k} = (k_x, k_y)$ in §12.E.2 is now replaced by

$$\mathbf{q} = (k_x, k_y) \quad \mathbf{k} = (k_x, k_y, k_z) = (\mathbf{q}, k_z)$$

The 3-D critical wave-vector thus has magnitude

$$k_c^2 = q_c^2 + k_{zc}^2 = \frac{3}{2} \left(\frac{\pi}{d} \right)^2 = 3 q_c^2 \quad (12.111b)$$

and

$$\mathcal{R}_c = 3 k_c^4 d^4 = \frac{27}{4} \pi^4 \quad (12.111c)$$

Consider now the case where \mathcal{R} is just below \mathcal{R}_c . Although the fluid is isotropic, fluctuations that excite the new mode described above will survive longer and longer as \mathcal{R} approaches \mathcal{R}_c ; until they become stable at $\mathcal{R} = \mathcal{R}_c$. This is called **critical slowly down**. Thus, all other fluctuations can be taken as background noises and described by the random noise correlation functions discussed in §S10.F.

S12.A.1.1. Equations of Motion

As in (10.313-4) of §S10.F.1, the addition of random forces turns the linearized equations (12.90-1) of §12.E.1 into

$$\rho_0 \frac{\partial \mathbf{v}}{\partial t} = \rho_0 \alpha_P \delta T g \hat{\mathbf{z}} - \nabla_r \delta P + \eta \nabla_r^2 \mathbf{v} - \nabla_r \cdot \mathbb{S} \quad (12.112)$$

$$\rho_0 \tilde{c}_p \left(\frac{\partial \delta T}{\partial t} - a v_z \right) = K \nabla_r^2 \delta T - \nabla_r \cdot \mathbf{g}_s \quad (12.113)$$

where \mathbf{g}_s & \mathbb{S} are the random heat flux and random stress tensor defined in (10.310-1), respectively. The symbol \mathbf{g}_s is used to avoid confusion with the acceleration of gravity g .

As in §12.E.1, we consider only the z-component of \mathbf{v} . Following the procedure that led to (10.94), the z-component of $\nabla_r \times \nabla_r \times$ (12.112) gives

$$\frac{\partial \nabla_r^2 v_z}{\partial t} = -\alpha_P g \frac{\partial^2 \delta T}{\partial z^2} + \alpha_P g \nabla_r^2 \delta T + \nu_t \nabla_r^4 v_z \quad (12.114)$$

$$+ \frac{1}{\rho_0} \mathbf{z} \cdot \{ \nabla_r \times [\nabla_r \times (\nabla_r \cdot \mathbb{S})] \}$$

$$= \alpha_P g \left(\frac{\partial^2 \delta T}{\partial x^2} + \frac{\partial^2 \delta T}{\partial y^2} \right) + \nu_t \nabla_r^4 v_z \quad (12.114a)$$

$$+ \frac{1}{\rho_0} \mathbf{z} \cdot \{ \nabla_r \times [\nabla_r \times (\nabla_r \cdot \mathbb{S})] \}$$

Owing to the general boundary conditions (12.95-6), a single component of the Fourier transform takes the form

$$v_z(\mathbf{r}, t) = \tilde{v}_z(\mathbf{k}, \omega) e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t} \sin k_z z \quad (12.115a)$$

$$\delta T(\mathbf{r}, t) = \tilde{T}(\mathbf{k}, \omega) e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t} \sin k_z z \quad (12.115b)$$

where

$$\mathbf{r}_\perp = (x, y) = x \hat{\mathbf{x}} + y \hat{\mathbf{y}} \quad (12.115c)$$

Since only the divergences of \mathbb{S} & \mathbf{g}_s appear in (12.113-4), both of their $\sin k_z z$ & $\cos k_z z$ components will be involved. Reverting to the exponential form, we write

$$v_z(\mathbf{r}, t) = \tilde{v}_{z\pm} e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\delta T(\mathbf{r}, t) = \tilde{T}_\pm e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\mathbb{S}(\mathbf{r}, t) = \tilde{\mathbb{S}}_\pm e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\mathbf{g}_s(\mathbf{r}, t) = \tilde{\mathbf{g}}_{s\pm} e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t} \quad (12.115d)$$

where

$$\tilde{X}_\pm \equiv \tilde{X}(\mathbf{k}_\pm, \omega) \quad \mathbf{k}_\pm = \mathbf{q} \pm k_z \hat{\mathbf{z}} \quad k_\pm^2 = q^2 + k_z^2 = k^2$$

while (12.115a-b) are recovered by setting

$$\tilde{v}_{z-} = -\tilde{v}_{z+} \quad \tilde{T}_- = -\tilde{T}_+$$

$$\tilde{v}_z = \frac{1}{2i} (\tilde{v}_{z+} - \tilde{v}_{z-}) \quad \tilde{T} = \frac{1}{2i} (\tilde{T}_+ - \tilde{T}_-) \quad (12.115e)$$

Thus,

$$\nabla_r v_z(\mathbf{r}, t) = i \mathbf{k}_\pm \tilde{v}_{z\pm} e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\nabla_r^2 v_z(\mathbf{r}, t) = -k^2 \tilde{v}_{z\pm} e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\rightarrow \nabla_r^4 v_z(\mathbf{r}, t) = -k^2 \nabla_r^2 v_z(\mathbf{r}, t) = k^4 \tilde{v}_{z\pm} e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

Similarly,

$$\nabla_r^2 \delta T(\mathbf{r}, t) = -k^2 \tilde{T}_\pm e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\nabla_r \cdot \mathbf{g}_s = i \mathbf{k}_\pm \cdot \tilde{\mathbf{g}}_\pm e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

and

$$\nabla_r \cdot \mathbb{S} = i \mathbf{k}_\pm \cdot \tilde{\mathbb{S}}_\pm e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\nabla_r \times (\nabla_r \cdot \mathbb{S}) = - [(\mathbf{k}_\pm \times (\mathbf{k}_\pm \cdot \tilde{\mathbb{S}}_\pm))] e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

$$\nabla_r \times [\nabla_r \times (\nabla_r \cdot \mathbb{S})]$$

$$= -i \{ \mathbf{k}_\pm \times [\mathbf{k}_\pm \times (\mathbf{k}_\pm \cdot \tilde{\mathbb{S}}_\pm)] \} e^{\pm i k_z z} e^{i\mathbf{q} \cdot \mathbf{r}_\perp} e^{-i\omega t}$$

Putting the above into (12.113-4) gives

$$i \omega k^2 \tilde{v}_{z\pm} + \alpha_P g q^2 \tilde{T}_\pm - \nu_t k^4 \tilde{v}_{z\pm}$$

$$= \frac{i}{\rho_0} \mathbf{z} \cdot \{ \mathbf{k}_\pm \times [\mathbf{k}_\pm \times (\mathbf{k}_\pm \cdot \tilde{\mathbb{S}}_\pm)] \} \quad (12.116a)$$

and

$$\rho_0 \tilde{c}_\rho (-i \omega \tilde{T}_\pm - a \tilde{v}_{z\pm}) + K k^2 \tilde{T}_\pm = i \mathbf{k}_\pm \cdot \tilde{\mathbf{g}}_\pm \quad (12.116b)$$

Note that the conditions (12.115e) imply

$$\begin{aligned} \hat{\mathbf{z}} \cdot [\mathbf{k}_- \times (\mathbf{k}_- \times (\mathbf{k}_- \cdot \tilde{\mathbf{S}}_-))] &= -\hat{\mathbf{z}} \cdot [\mathbf{k}_+ \times (\mathbf{k}_+ \times (\mathbf{k}_+ \cdot \tilde{\mathbf{S}}_+))] \\ \mathbf{k}_- \cdot \tilde{\mathbf{g}}_- &= -\mathbf{k}_+ \cdot \tilde{\mathbf{g}}_+ \end{aligned} \quad (12.116c)$$

In matrix form,

$$\begin{pmatrix} v_t k^2 - i\omega & -\frac{\alpha_P g}{k^2} q^2 \\ -a & \frac{K k^2}{\rho_0 \tilde{c}_p} - i\omega \end{pmatrix} \begin{pmatrix} \tilde{v}_{z\pm} \\ \tilde{T}_{\pm} \end{pmatrix} = \begin{pmatrix} -\frac{i}{k^2 \rho_0} \mathbf{z} \cdot \{\mathbf{k}_{\pm} \times [\mathbf{k}_{\pm} \times (\mathbf{k}_{\pm} \cdot \tilde{\mathbf{S}}_{\pm})]\} \\ \frac{i}{\rho_0 \tilde{c}_p} \mathbf{k}_{\pm} \cdot \tilde{\mathbf{g}}_{\pm} \end{pmatrix}$$

which can be combined to give

$$\begin{aligned} &\begin{pmatrix} v_t k^2 - i\omega & -\frac{\alpha_P g}{k^2} q^2 \\ -a & \frac{K k^2}{\rho_0 \tilde{c}_p} - i\omega \end{pmatrix} \begin{pmatrix} \tilde{v}_z \\ \tilde{T} \end{pmatrix} \\ &= \begin{pmatrix} -\frac{1}{2 k^2 \rho_0} \hat{\mathbf{z}} \cdot [\mathbf{k}_+ \times (\mathbf{k}_+ \times (\mathbf{k}_+ \cdot \tilde{\mathbf{S}}_+)) - \mathbf{k}_- \times (\mathbf{k}_- \times (\mathbf{k}_- \cdot \tilde{\mathbf{S}}_-))] \\ \frac{1}{2 \rho_0 \tilde{c}_p} (\mathbf{k}_+ \cdot \tilde{\mathbf{g}}_+ - \mathbf{k}_- \cdot \tilde{\mathbf{g}}_-) \end{pmatrix} \end{aligned} \quad (12.116)$$

S12.A.1.21. The Critical Eigenmode

(12.116) can be written as

$$(\omega \mathbb{I} + i\mathbb{M}) \mathbf{v} = \mathbf{s} \quad (12.117a)$$

where

$$\mathbb{M} = \begin{pmatrix} v_t k^2 & -\frac{\alpha_P g}{k^2} q^2 \\ -a & \frac{K k^2}{\rho_0 \tilde{c}_p} \end{pmatrix} \quad \mathbf{v} = \begin{pmatrix} \tilde{v}_z \\ \tilde{T} \end{pmatrix} \quad (12.117b)$$

$$\mathbf{s} = \begin{pmatrix} -\frac{i}{2 k^2 \rho_0} \hat{\mathbf{z}} \cdot [\mathbf{k}_+ \times (\mathbf{k}_+ \times (\mathbf{k}_+ \cdot \tilde{\mathbf{S}}_+)) - \mathbf{k}_- \times (\mathbf{k}_- \times (\mathbf{k}_- \cdot \tilde{\mathbf{S}}_-))] \\ \frac{i}{2 \rho_0 \tilde{c}_p} (\mathbf{k}_+ \cdot \tilde{\mathbf{g}}_+ - \mathbf{k}_- \cdot \tilde{\mathbf{g}}_-) \end{pmatrix} \quad (12.117c)$$

In terms of the Rayleigh and Prandtl numbers [see (12.107) of §12.E.2]

$$\begin{aligned} \mathcal{R} &= \frac{\alpha_P g \rho_0 \tilde{c}_p a}{v_t K} d^4 & \rightarrow & \frac{K}{\rho_0 \tilde{c}_p} = \frac{\alpha_P g a}{v_t \mathcal{R}} d^4 \\ \mathcal{P} &= \frac{v_t \rho_0 \tilde{c}_p}{K} & \rightarrow & \frac{K}{\rho_0 \tilde{c}_p} = \frac{v_t}{\mathcal{P}} \end{aligned}$$

(12.117b) becomes

$$\mathbb{M} = \begin{pmatrix} v_t k^2 & -\frac{\alpha_P g}{k^2} q^2 \\ -a & \frac{a \alpha_P g d^4 k^2}{v_t \mathcal{R}} \end{pmatrix} = \begin{pmatrix} v_t k^2 & -\frac{\alpha_P g}{k^2} q^2 \\ -a & \frac{v_t k^2}{\mathcal{P}} \end{pmatrix} \quad (12.117d)$$

At the critical point [see (12.111a-c)], (12.117d) becomes

$$\mathbb{M}_c = \begin{pmatrix} v_t k_c^2 & -\frac{\alpha_P g}{k_c^2} q_c^2 \\ -a & \frac{a \alpha_P g d^4 k_c^2}{v_t \mathcal{R}_c} \end{pmatrix} = \begin{pmatrix} \frac{3 \pi^2 v_t}{2 d^2} & -\frac{\alpha_P g}{3} \\ -a & \frac{2 a \alpha_P g d^2}{9 \pi^2 v_t} \end{pmatrix} \quad (12.118)$$

$$= \begin{pmatrix} v_t k_c^2 & -\frac{\alpha_P g}{3} \\ -a & \frac{a \alpha_P g}{3 v_t k_c^2} \end{pmatrix} \quad (12.118a)$$

The eigenvalues of M_c are obtained using the *Mathematica* code in §Code, giving

$$\lambda_s^c = 0 \quad \lambda_f^c = \frac{27 \pi^4 v_t^2 + 4 a d^4 g \alpha_P}{18 d^2 \pi^2 v_t} \quad (12.119)$$

$$= \frac{6 k_c^4 v_t^2 + 2 a g \alpha_P}{6 k_c^2 v_t}$$

The left and right eigenvectors for $\lambda_s^c = 0$ are

$$\chi_s^c = C \begin{pmatrix} \frac{2 a d^2}{3 \pi^2 v_t}, 1 \end{pmatrix} = C' \begin{pmatrix} a \\ k_c^2 v_t, 1 \end{pmatrix} \quad (12.120a)$$

$$\psi_s^c = C \begin{pmatrix} \frac{2 d^2 g \alpha_P}{9 \pi^2 v_t} \\ 1 \end{pmatrix} = C' \begin{pmatrix} g \alpha_P \\ 3 k_c^2 v_t \\ 1 \end{pmatrix} \quad (12.120b)$$

where C & C' are normalization constants.

With the normalization

$$\chi_s^c \psi_s^c = 1 \quad (12.120c)$$

we have

$$C^2 \left(\frac{4 a d^4 g \alpha_P}{27 \pi^4 v_t^2} + 1 \right) = 1$$

$$\rightarrow C = \frac{3 \sqrt{3} \pi^2 v_t}{\sqrt{4 a d^4 g \alpha_P + 27 \pi^4 v_t^2}} \quad (12.121a)$$

Note that (12.120a) & (12.121a) are the same as Reichl's (12.120-1) if we set

$$C = \frac{3 \pi^2 v_t}{2 a d^2} A$$

Similarly,

$$C'^2 \left(\frac{a g \alpha_P}{3 k_c^4 v_t^2} + 1 \right) = 1$$

Using

$$\frac{a g \alpha_P}{v_t^2} = \frac{\mathcal{R}}{\mathcal{P} d^4} \quad (12.121b)$$

we have

$$\frac{a g \alpha_P}{3 k_c^4 v_t^2} = \frac{\mathcal{R}}{3 k_c^4 \mathcal{P} d^4} = \frac{\mathcal{R}}{\mathcal{R}_c \mathcal{P}}$$

$$\rightarrow C' = \frac{1}{\sqrt{\frac{\mathcal{R}}{\mathcal{R}_c \mathcal{P}} + 1}} \quad (12.121c)$$

The eigenvectors for λ_f^c can be found in §Code but won't be discussed here.

Eigenvalues & eigenvectors of \mathbb{M} near the critical point with $\mathcal{R} < \mathcal{R}_c$ can be obtained by perturbation techniques. Thus, we set

$$\mathcal{R} = \mathcal{R}_c (1 - \delta \mathcal{R}) = \frac{27 \pi^2}{4} (1 - \delta \mathcal{R}) \quad (\delta \mathcal{R} > 0) \quad (12.121d)$$

Keeping

$$k_z = k_{cz} = \frac{\pi}{d} \quad (12.121e)$$

we set

$$q^2 = q_c^2 (1 + \delta q) = \frac{\pi^2}{2 d^2} (1 + \delta q) \quad (12.121f)$$

$$\begin{aligned} \rightarrow \quad k^2 &= q^2 + k_{cz}^2 = q_c^2 (1 + \delta q) + k_{cz}^2 = k_c^2 + q_c^2 \delta q \\ \frac{q^2}{k^2} &= \frac{q_c^2 (1 + \delta q)}{k_c^2 + q_c^2 \delta q} = \frac{q_c^2}{k_c^2} (1 + \delta q) \left(1 + \frac{q_c^2}{k_c^2} \delta q \right)^{-1} \\ &= \frac{q_c^2}{k_c^2} \left[1 + \left(1 - \frac{q_c^2}{k_c^2} \right) \delta q - \left(1 - \frac{q_c^2}{k_c^2} \right) \left(\frac{q_c^2}{k_c^2} \right) (\delta q)^2 + \dots \right] \\ &= \frac{1}{3} \left(1 + \frac{2}{3} \delta q - \frac{2}{9} (\delta q)^2 \right) + O(\delta q)^3 \\ \frac{k^2}{\mathcal{R}} &= \frac{k_c^2 + q_c^2 \delta q}{\mathcal{R}_c (1 - \delta \mathcal{R})} = \frac{k_c^2}{\mathcal{R}_c} \left(1 + \frac{q_c^2}{k_c^2} \delta q \right) (1 - \delta \mathcal{R})^{-1} = \frac{k_c^2}{\mathcal{R}_c} \left(1 + \frac{q_c^2}{k_c^2} \delta q + \delta \mathcal{R} + \dots \right) \\ &= \frac{k_c^2}{\mathcal{R}_c} \left(1 + \frac{1}{3} \delta q + \delta \mathcal{R} \right) + O(\delta \mathcal{R})^2 \end{aligned}$$

(12.117d) then becomes

$$\mathbb{M} \approx \begin{pmatrix} v_t k_c^2 + v_t q_c^2 \delta q & -\frac{\alpha_p g}{3} \left(1 + \frac{2}{3} \delta q - \frac{2}{9} (\delta q)^2 \right) \\ -a & \frac{v_t k_c^2}{\mathcal{P}} \left(1 + \frac{1}{3} \delta q + \delta \mathcal{R} \right) \end{pmatrix} \quad (12.122a)$$

where we have assumed $\frac{a \alpha_p g}{v_t}$ is kept constant at the value when $\mathcal{R} = \mathcal{R}_c$ so that

$$\mathcal{P} = \frac{v_t^2 \mathcal{R}_c}{a g \alpha_p d^4}$$

The $(\delta q)^2$ term is included since it turns out that the δq terms make no net correction to the eigenvalues.

In general, given the right and left eigenvector equations

$$(\mathbb{H} - \lambda \mathbb{I}) \mathbf{v} = 0 \quad \mathbf{u}^T (\mathbb{H} - \lambda \mathbb{I}) = 0 \quad (12.122b)$$

adding a perturbation $\delta \mathbb{H}$ to \mathbb{H} leads to the eigen-equation

$$\left[\mathbb{H} + \delta \mathbb{H} - (\lambda + \delta \lambda) \mathbb{I} \right] (\mathbf{v} + \delta \mathbf{v}) = 0 \quad (12.122c)$$

\mathbf{u}^T (12.122 c) then gives

$$\mathbf{u}^T (\delta \mathbb{H} - \delta \lambda \mathbb{I}) (\mathbf{v} + \delta \mathbf{v}) = 0$$

Assuming the normalization

$$\mathbf{u}^T \mathbf{v} = 1$$

we have

$$\delta \lambda (1 + \mathbf{u}^T \delta \mathbf{v}) = \mathbf{u}^T \delta \mathbb{H} (\mathbf{v} + \delta \mathbf{v}) \quad (12.122d)$$

which, to 1st order of all variations, gives

$$\delta \lambda = \mathbf{u}^T \delta \mathbb{H} \mathbf{v} \quad (12.122e)$$

Applying (12.122e) to (12.122a) then gives

$$\begin{aligned} \delta \lambda_s^c &= \mathbf{X}_s^c \delta \mathbb{M} \boldsymbol{\Psi}_s^c \\ &= C^{\cdot 2} \begin{pmatrix} \frac{a}{k_c^2 v_t}, 1 \end{pmatrix} \begin{pmatrix} v_t q_c^2 \delta q & -\frac{2 \alpha_P g}{9} \left(\delta q - \frac{1}{3} (\delta q)^2 \right) \\ 0 & \frac{v_t k_c^2}{\mathcal{P}} \left(\frac{1}{3} \delta q + \delta \mathcal{R} \right) \end{pmatrix} \begin{pmatrix} \frac{g \alpha_P}{3 k_c^2 v_t} \\ 1 \end{pmatrix} \\ &= C^{\cdot 2} \begin{pmatrix} \frac{a}{k_c^2 v_t}, 1 \end{pmatrix} \begin{pmatrix} -\frac{\alpha_P g}{9} \left(\delta q - \frac{2}{3} (\delta q)^2 \right) \\ \frac{v_t k_c^2}{\mathcal{P}} \left(\frac{1}{3} \delta q + \delta \mathcal{R} \right) \end{pmatrix} \\ &= C^{\cdot 2} \left[\left(-\frac{a \alpha_P g}{9 k_c^2 v_t} + \frac{v_t k_c^2}{3 \mathcal{P}} \right) \delta q + \frac{2 a \alpha_P g}{27 k_c^2 v_t} (\delta q)^2 + \frac{v_t k_c^2}{\mathcal{P}} \delta \mathcal{R} \right] \\ &= \frac{\mathcal{P}}{\frac{\mathcal{R}}{\mathcal{R}_c} + \mathcal{P}} \left[\left(-\frac{a \alpha_P g}{9 k_c^2 v_t} + \frac{v_t k_c^2}{3 \mathcal{P}} \right) \delta q + \frac{2 a \alpha_P g}{27 k_c^2 v_t} (\delta q)^2 + \frac{v_t k_c^2}{\mathcal{P}} \delta \mathcal{R} \right] \end{aligned}$$

Since

$$\frac{a \alpha_P g}{9 k_c^2 v_t} = \frac{v_t k_c^2}{3 \mathcal{P}}$$

we have

$$\begin{aligned} \delta \lambda_s^c &= \frac{v_t k_c^2}{1 - \frac{\delta \mathcal{R}}{\mathcal{R}_c} + \mathcal{P}} \left(\frac{2}{9} (\delta q)^2 + \delta \mathcal{R} \right) \\ &\approx \frac{v_t k_c^2}{1 + \mathcal{P}} \left(\frac{2}{9} (\delta q)^2 + \delta \mathcal{R} \right) \\ &= \frac{v_t k_c^2}{1 + \mathcal{P}} \left[\frac{2}{9} \left(\frac{q^2 - q_c^2}{q_c^2} \right)^2 + \frac{\mathcal{R}_c - \mathcal{R}}{\mathcal{R}_c} \right] \\ &= \frac{v_t k_c^2}{1 + \mathcal{P}} \left[\frac{2}{3} \frac{(q^2 - q_c^2)^2}{k_c^2 q_c^2} + \frac{\mathcal{R}_c - \mathcal{R}}{\mathcal{R}_c} \right] \quad (12.122) \end{aligned}$$

Code

$$\mathbb{M} = \begin{pmatrix} \mathbf{A} & -\mathbf{B} \\ -\mathbf{a} & \mathbf{F} \end{pmatrix};$$

(* eigenvalues & eigenvectors for M_c *)

$$\text{par} = \left\{ A \rightarrow \frac{3 \pi^2 v_t}{2 d^2}, B \rightarrow \frac{\alpha_p g}{3}, F \rightarrow \frac{2 a \alpha_p g d^2}{9 \pi^2 v_t} \right\};$$

$\{\lambda R, \text{evR}\} = \text{Eigensystem}[M] /. \text{par} // \text{Simplify} // \text{PowerExpand}$

$\{\lambda L, \text{evL}\} = \text{Eigensystem}[M^T] /. \text{par} // \text{Simplify} // \text{PowerExpand}$

$$\left\{ \left\{ \theta, \frac{54 \pi^4 v_t^2 + 8 a d^4 g \alpha_p}{36 d^2 \pi^2 v_t} \right\}, \left\{ \left\{ \frac{2 d^2 g \alpha_p}{9 \pi^2 v_t}, 1 \right\}, \left\{ -\frac{3 \pi^2 v_t}{2 a d^2}, 1 \right\} \right\} \right\}$$

$$\left\{ \left\{ \theta, \frac{54 \pi^4 v_t^2 + 8 a d^4 g \alpha_p}{36 d^2 \pi^2 v_t} \right\}, \left\{ \left\{ \frac{2 a d^2}{3 \pi^2 v_t}, 1 \right\}, \left\{ -\frac{9 \pi^2 v_t}{2 d^2 g \alpha_p}, 1 \right\} \right\} \right\}$$

(* eigenvalues & eigenvectors for M_c expressed in terms of k_c *)

$$\text{parkc} = \left\{ A \rightarrow v_t k_c^2, B \rightarrow \frac{g \alpha_p}{3}, F \rightarrow \frac{a g \alpha_p}{3 v_t k_c^2} \right\};$$

$\{\lambda Rk_c, \text{evRk}_c\} = \text{Eigensystem}[M] /. \text{parkc} // \text{Simplify} // \text{PowerExpand}$

$\{\lambda Lk_c, \text{evLk}_c\} = \text{Eigensystem}[M^T] /. \text{parkc} // \text{Simplify} // \text{PowerExpand}$

$$\left\{ \left\{ \theta, \frac{6 k_c^4 v_t^2 + 2 a g \alpha_p}{6 k_c^2 v_t} \right\}, \left\{ \left\{ \frac{g \alpha_p}{3 k_c^2 v_t}, 1 \right\}, \left\{ -\frac{k_c^2 v_t}{a}, 1 \right\} \right\} \right\}$$

$$\left\{ \left\{ \theta, \frac{6 k_c^4 v_t^2 + 2 a g \alpha_p}{6 k_c^2 v_t} \right\}, \left\{ \left\{ \frac{a}{k_c^2 v_t}, 1 \right\}, \left\{ -\frac{3 k_c^2 v_t}{g \alpha_p}, 1 \right\} \right\} \right\}$$

$$\text{park} = \left\{ A \rightarrow v_t k^2, B \rightarrow g \alpha_p \frac{q^2}{k^2}, F \rightarrow \frac{v_t k^2}{p} \right\};$$

$\{\lambda Rk, \text{evRk}\} = \text{Eigensystem}[M] /. \text{park} // \text{Simplify} // \text{PowerExpand}$

$\{\lambda Lk, \text{evLk}\} = \text{Eigensystem}[M^T] /. \text{park} // \text{Simplify} // \text{PowerExpand}$

$$\left\{ \left\{ \frac{k^2 (1+P) v_t - \frac{\sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p}}{k}}{2 P}, \frac{k^2 (1+P) v_t + \frac{\sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p}}{k}}{2 P} \right\}, \right.$$

$$\left. \left\{ \left\{ \frac{-k^2 (-1+P) v_t + \frac{\sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p}}{k}}{2 a P}, 1 \right\}, \left\{ -\frac{k^2 (-1+P) v_t + \frac{\sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p}}{k}}{2 a P}, 1 \right\} \right\} \right\}$$

$$\left\{ \left\{ \frac{k^2 (1+P) v_t - \frac{\sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p}}{k}}{2 P}, \frac{k^2 (1+P) v_t + \frac{\sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p}}{k}}{2 P} \right\}, \right.$$

$$\left. \left\{ \left\{ \frac{1}{2 g P q^2 \alpha_p} \left(-k^4 (-1+P) v_t + k \sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p} \right), 1 \right\}, \right. \right.$$

$$\left. \left\{ -\frac{1}{2 g P q^2 \alpha_p} \left(k^4 (-1+P) v_t + k \sqrt{k^6 (-1+P)^2 v_t^2 + 4 a g P^2 q^2 \alpha_p} \right), 1 \right\} \right\}$$

$$\text{par}\delta = \left\{ a \rightarrow \theta, A \rightarrow v_t q_c^2 \delta q, B \rightarrow \frac{\alpha_p g}{3} \frac{q_c^2}{k_c^2} \left(1 - \frac{q_c^2}{k_c^2} \right) \delta q, F \rightarrow \frac{a \alpha_p g d^4 k_c^2}{R_c v_t} \left(\frac{q_c^2}{k_c^2} \delta q - \delta R \right) \right\};$$

$\delta\lambda = \text{evL}[[1]].(M /. \text{par}\delta). \text{evR}[[1]] // \text{Simplify}$

$$\frac{1}{27 v_t^2} a d^2 g \left(\frac{4 d^2 \delta q q_c^2 v_t}{\pi^4} + \frac{6 \delta q q_c^2 (-k_c^2 + q_c^2) v_t}{\pi^2 k_c^4} - \frac{27 d^2 (\delta R k_c^2 - \delta q q_c^2) v_t}{R_c} \right) \alpha_p$$

Collect[$\delta\lambda$, { δq , δR }]

$$-\frac{a d^4 g \delta R k_c^2 \alpha_p}{R_c v_t} + \frac{a d^2 g \delta q \left(\frac{4 d^2 q_c^2 v_t}{\pi^4} + \frac{6 q_c^2 (-k_c^2 + q_c^2) v_t}{\pi^2 k_c^4} + \frac{27 d^2 q_c^2 v_t}{R_c} \right) \alpha_p}{27 v_t^2}$$

CoefficientList[$\delta\lambda$, { δq , δR }]

$$\left\{ \left\{ \theta, -\frac{a d^4 g k_c^2 \alpha_p}{R_c v_t} \right\}, \left\{ \frac{4 a d^4 g q_c^2 v_t \alpha_p}{27 \pi^4 v_t^2} + \frac{2 a d^2 g q_c^2 (-k_c^2 + q_c^2) \alpha_p}{9 \pi^2 k_c^4 v_t} + \frac{a d^4 g q_c^2 \alpha_p}{R_c v_t}, \theta \right\} \right\}$$

q

CoefficientList[$1 + a x^2 + b x y + c y^2$, { x , y }] // **MatrixForm**

$$\begin{pmatrix} 1 & 0 & c \\ 0 & b & 0 \\ a & 0 & 0 \end{pmatrix}$$

$$\text{par}\delta = \left\{ A \rightarrow \frac{3 \pi^2 v_t}{2 d^2} \left(1 + \frac{1}{3} \delta q \right), B \rightarrow \frac{\alpha_p g}{3} \left(1 + \frac{2}{3} \delta q \right), R \rightarrow \frac{2 a \alpha_p g d^2}{9 \pi^2 v_t} \left(1 - \frac{2}{3} \delta q \right) \right\};$$

{ $\lambda R \delta$, $\text{ev} R \delta$ } = **Eigensystem**[M] /. **par** δ // **Simplify**;

({ $\lambda R \delta$, $\text{ev} R \delta$ } // **PowerExpand**) + $O[\delta q]^2$) // **PowerExpand**

$$\left\{ \left\{ \frac{81 \pi^4 v_t^2 + 12 a d^4 g \alpha_p - 3 (27 \pi^4 v_t^2 + 4 a d^4 g \alpha_p)}{108 d^2 \pi^2 v_t} + \frac{1}{108 d^2 \pi^2 v_t} \right. \right. \\ \left. \left. (27 \pi^4 v_t^2 - 8 a d^4 g \alpha_p + (-729 \pi^8 v_t^4 - 540 a d^4 g \pi^4 v_t^4 \alpha_p + 32 a^2 d^8 g^2 \alpha_p^2) / (27 \pi^4 v_t^2 + 4 a d^4 g \alpha_p)) \delta q + \right. \right. \\ \left. \left. O[\delta q]^2, \frac{54 \pi^4 v_t^2 + 8 a d^4 g \alpha_p}{36 d^2 \pi^2 v_t} + \frac{1}{108 d^2 \pi^2 v_t} \right. \right. \\ \left. \left. \left(27 \pi^4 v_t^2 - 8 a d^4 g \alpha_p + \frac{729 \pi^8 v_t^4 + 540 a d^4 g \pi^4 v_t^4 \alpha_p - 32 a^2 d^8 g^2 \alpha_p^2}{27 \pi^4 v_t^2 + 4 a d^4 g \alpha_p} \right) \delta q + O[\delta q]^2 \right\}, \left\{ \left\{ \frac{2 d^2 g \alpha_p}{9 \pi^2 v_t} + \right. \right. \right. \\ \left. \left. \left((-27 \pi^4 v_t^2 - 8 a d^4 g \alpha_p + (729 \pi^8 v_t^4 + 540 a d^4 g \pi^4 v_t^4 \alpha_p - 32 a^2 d^8 g^2 \alpha_p^2) / (27 \pi^4 v_t^2 + 4 a d^4 g \alpha_p)) \right. \right. \right. \\ \left. \left. \left. \delta q \right) / (108 a d^2 \pi^2 v_t) + O[\delta q]^2, 1 + O[\delta q]^2 \right\}, \left\{ -\frac{3 (\pi^2 v_t)}{2 (a d^2)} + \right. \right. \\ \left. \left. \left((-27 \pi^4 v_t^2 - 8 a d^4 g \alpha_p - (729 \pi^8 v_t^4 + 540 a d^4 g \pi^4 v_t^4 \alpha_p - 32 a^2 d^8 g^2 \alpha_p^2) / (27 \pi^4 v_t^2 + 4 a d^4 g \alpha_p)) \right. \right. \right. \\ \left. \left. \left. \delta q \right) / (108 a d^2 \pi^2 v_t) + O[\delta q]^2, 1 + O[\delta q]^2 \right\} \right\}$$

($\lambda R \delta$ [1] /. **par** δ // **Simplify**) + $O[\delta q]^2$) // **PowerExpand** // **Simplify**

$$-\frac{6 (a d^2 g \pi^2 v_t \alpha_p) \delta q}{27 \pi^4 v_t^2 + 4 a d^4 g \alpha_p} + O[\delta q]^2$$

S12.A.1.3. Correlation Function for the Macroscopic Mode

We can isolate the critical eigenmode $\lambda_s^c = 0$ from the equations of motion by multiplying (12.116) on the left by χ_s^c to get

$$\chi_s^c (\mathbb{M} - i\omega \mathbb{I}) \begin{pmatrix} \tilde{v}_z \\ \tilde{T} \end{pmatrix} = \chi_s^c \begin{pmatrix} -\frac{1}{2k^2\rho_0} (S^+ - S^-) \\ \frac{1}{2\rho_0\tilde{c}_\rho} (G^+ - G^-) \end{pmatrix} \quad (12.123a)$$

where

$$S^\pm = \hat{z} \cdot [\mathbf{k}_\pm \times (\mathbf{k}_\pm \times (\mathbf{k}_\pm \cdot \tilde{\mathbf{S}}_\pm))] \quad G^\pm = \mathbf{k}_\pm \cdot \tilde{\mathbf{g}}_\pm \quad (12.123b)$$

Note that until we apply the conditions (12.116c), (12.123a) is valid for an isotropic system.

Near the critical point, 1st order perturbation gives

$$\chi_s^c \mathbb{M} \approx \chi_s^c \lambda_s$$

where λ_s is given by (12.122). Using

$$\begin{aligned} \chi_s^c &= C \left(\frac{2ad^2}{3\pi^2 v_t}, 1 \right) && \text{[see (12.120a)]} \\ &= C \left(\frac{a}{k_c^2 v_t}, 1 \right) && \text{[(12.111b) used.]} \end{aligned}$$

(12.123a) becomes

$$\begin{aligned} (\lambda_s - i\omega) \begin{pmatrix} \frac{a}{k_c^2 v_t}, 1 \end{pmatrix} \begin{pmatrix} \tilde{v}_z \\ \tilde{T} \end{pmatrix} &= \begin{pmatrix} \frac{a}{k_c^2 v_t}, 1 \end{pmatrix} \begin{pmatrix} -\frac{1}{2k^2\rho_0} (S^+ - S^-) \\ \frac{1}{2\rho_0\tilde{c}_\rho} (G^+ - G^-) \end{pmatrix} \\ \rightarrow (\lambda_s - i\omega) \begin{pmatrix} \frac{a}{k_c^2 v_t} \tilde{v}_z + \tilde{T} \end{pmatrix} &= -\frac{a}{2k_c^2 v_t k^2 \rho_0} (S^+ - S^-) + \frac{1}{2\rho_0\tilde{c}_\rho} (G^+ - G^-) \\ (\lambda_s - i\omega) \begin{pmatrix} \tilde{v}_z + \frac{v_t k_c^2}{a} \tilde{T} \end{pmatrix} &= -\frac{1}{2k^2\rho_0} (S^+ - S^-) + \frac{v_t k_c^2}{2a\rho_0\tilde{c}_\rho} (G^+ - G^-) \\ \rightarrow (i\lambda_s + \omega) \tilde{u}_q(\omega) &= -\frac{i}{2k^2\rho_0} (S^+ - S^-) + \frac{iv_t k_c^2}{2a\rho_0\tilde{c}_\rho} (G^+ - G^-) \end{aligned} \quad (12.123)$$

where

$$\begin{aligned} \tilde{u}_q(\omega) &= \tilde{v}_z + \frac{v_t k_c^2}{a} \tilde{T} \\ &\propto \chi_s^c \begin{pmatrix} \tilde{v}_z \\ \tilde{T} \end{pmatrix} \end{aligned} \quad (12.124)$$

is the critical mode.

The correlation function for the critical mode is therefore

$$\begin{aligned} \langle \tilde{u}_{q_1}(\omega_1) \tilde{u}_{q_2}(\omega_2) \rangle &= \frac{1}{(i\lambda_{s1} + \omega_1)(i\lambda_{s2} + \omega_2)} \\ &\quad \times \left\langle \left[-\frac{i}{2k_1^2\rho_0} (S_1^+ - S_1^-) + \frac{iv_t k_c^2}{2a\rho_0\tilde{c}_\rho} (G_1^+ - G_1^-) \right] \right. \\ &\quad \left. \times \left[-\frac{i}{2k_2^2\rho_0} (S_2^+ - S_2^-) + \frac{iv_t k_c^2}{2a\rho_0\tilde{c}_\rho} (G_2^+ - G_2^-) \right] \right\rangle \end{aligned}$$

$$= \frac{1}{4(i\lambda_{s1} + \omega_1)(i\lambda_{s2} + \omega_2)} \left[-\frac{1}{k_1^2 k_2^2 \rho_0^2} \langle (S_1^+ - S_1^-)(S_2^+ - S_2^-) \rangle \right. \\ \left. - \frac{v_t^2 K_c^4}{a^2 \rho_0^2 \tilde{c}_\rho^2} \langle (G_1^+ - G_1^-)(G_2^+ - G_2^-) \rangle \right] \quad (12.125)$$

where we have used the fact that any average involving odd powers of any components of the random forces \mathbb{S} or \mathbf{g}_s must vanish.

Now,

$$\begin{aligned} [\mathbf{k} \times (\mathbf{k} \cdot \tilde{\mathbb{S}})]_i &= \epsilon_{ijm} k_j k_n \tilde{S}_{nm} \\ [\mathbf{k} \times (\mathbf{k} \times (\mathbf{k} \cdot \tilde{\mathbb{S}}))]_a &= \epsilon_{abi} \epsilon_{ijm} k_b k_j k_n \tilde{S}_{nm} \\ &= (\delta_{aj} \delta_{bm} - \delta_{am} \delta_{bj}) k_b k_j k_n \tilde{S}_{nm} \\ &= k_m k_a k_n \tilde{S}_{nm} - k_j k_j k_n \tilde{S}_{na} \\ \hat{\mathbf{z}} \cdot [\mathbf{k} \times (\mathbf{k} \times (\mathbf{k} \cdot \tilde{\mathbb{S}}))] &= k_m k_z k_n \tilde{S}_{nm} - k_j k_j k_n \tilde{S}_{nz} \\ &= k_n (k_z k_m - k^2 \delta_{mz}) \tilde{S}_{nm} \end{aligned}$$

$$\rightarrow \hat{\mathbf{z}} \cdot [\mathbf{k}_\pm \times (\mathbf{k}_\pm \times (\mathbf{k}_\pm \cdot \tilde{\mathbb{S}}_\pm))] = k_n^\pm (k_z^\pm k_m^\pm - k^2 \delta_{mz}) \tilde{S}_{nm}^\pm$$

where

$$k^\pm{}^2 = (\mathbf{q} \pm k_z \hat{\mathbf{z}})^2 = q^2 + k_z^2 = k^2$$

Hence,

$$\begin{aligned} &\langle (S_1^+ - S_1^-)(S_2^+ - S_2^-) \rangle \\ &= \langle [k_{1n}^+ (k_{1z}^+ k_{1m}^+ - k_1^2 \delta_{mz}) \tilde{S}_{nm}^+(\mathbf{k}_1^+, \omega_1) - k_{1n}^- (k_{1z}^- k_{1m}^- - k_1^2 \delta_{mz}) \tilde{S}_{nm}^-(\mathbf{k}_1^-, \omega_1)] \\ &\quad \times [k_{2i}^+ (k_{2z}^+ k_{2j}^+ - k_2^2 \delta_{jz}) \tilde{S}_{ij}^+(\mathbf{k}_2^+, \omega_2) - k_{2i}^- (k_{2z}^- k_{2j}^- - k_2^2 \delta_{jz}) \tilde{S}_{ij}^-(\mathbf{k}_2^-, \omega_2)] \rangle \\ &= k_{1n}^+ (k_{1z}^+ k_{1m}^+ - k_1^2 \delta_{mz}) k_{2i}^+ (k_{2z}^+ k_{2j}^+ - k_2^2 \delta_{jz}) \langle \tilde{S}_{nm}^+(\mathbf{k}_1^+, \omega_1) \tilde{S}_{ij}^+(\mathbf{k}_2^+, \omega_2) \rangle \\ &\quad + k_{1n}^- (k_{1z}^- k_{1m}^- - k_1^2 \delta_{mz}) k_{2i}^- (k_{2z}^- k_{2j}^- - k_2^2 \delta_{jz}) \langle \tilde{S}_{nm}^-(\mathbf{k}_1^-, \omega_1) \tilde{S}_{ij}^-(\mathbf{k}_2^-, \omega_2) \rangle \\ &\quad - k_{1n}^+ (k_{1z}^+ k_{1m}^+ - k_1^2 \delta_{mz}) k_{2i}^- (k_{2z}^- k_{2j}^- - k_2^2 \delta_{jz}) \langle \tilde{S}_{nm}^+(\mathbf{k}_1^+, \omega_1) \tilde{S}_{ij}^-(\mathbf{k}_2^-, \omega_2) \rangle \\ &\quad - k_{1n}^- (k_{1z}^- k_{1m}^- - k_1^2 \delta_{mz}) k_{2i}^+ (k_{2z}^+ k_{2j}^+ - k_2^2 \delta_{jz}) \langle \tilde{S}_{nm}^-(\mathbf{k}_1^-, \omega_1) \tilde{S}_{ij}^+(\mathbf{k}_2^+, \omega_2) \rangle \end{aligned}$$

Using the relations derived for an isotropic system [see (10.349) of §S10.F.3]

$$\begin{aligned} \langle \tilde{S}_{nm}(\mathbf{k}, \omega) \tilde{S}_{ij}(\mathbf{k}', \omega') \rangle &= 4 \pi k_B T \left[\eta (\delta_{ni} \delta_{mj} + \delta_{nj} \delta_{mi}) \right. \\ &\quad \left. + \left(\zeta - \frac{2}{3} \eta \right) \delta_{nm} \delta_{ij} \right] \delta(\mathbf{k} + \mathbf{k}') \delta(\omega + \omega') \end{aligned}$$

we have

$$\begin{aligned} \mathfrak{S} &= \langle (S_1^+ - S_1^-)(S_2^+ - S_2^-) \rangle \\ &= \langle S_1^+ S_2^+ \rangle + \langle S_1^- S_2^- \rangle - \langle S_1^+ S_2^- \rangle - \langle S_1^- S_2^+ \rangle \\ &= 4 \pi k_B T \left\{ k_{1n}^+ (k_{1z}^+ k_{1m}^+ - k_1^2 \delta_{mz}) k_{2i}^+ (k_{2z}^+ k_{2j}^+ - k_2^2 \delta_{jz}) \delta(\mathbf{k}_1^+ + \mathbf{k}_2^+) \right. \\ &\quad + k_{1n}^- (k_{1z}^- k_{1m}^- - k_1^2 \delta_{mz}) k_{2i}^- (k_{2z}^- k_{2j}^- - k_2^2 \delta_{jz}) \delta(\mathbf{k}_1^- + \mathbf{k}_2^-) \\ &\quad - k_{1n}^+ (k_{1z}^+ k_{1m}^+ - k_1^2 \delta_{mz}) k_{2i}^- (k_{2z}^- k_{2j}^- - k_2^2 \delta_{jz}) \delta(\mathbf{k}_1^+ + \mathbf{k}_2^-) \\ &\quad \left. - k_{1n}^- (k_{1z}^- k_{1m}^- - k_1^2 \delta_{mz}) k_{2i}^+ (k_{2z}^+ k_{2j}^+ - k_2^2 \delta_{jz}) \delta(\mathbf{k}_1^- + \mathbf{k}_2^+) \right\} \\ &\quad \times \left[\eta (\delta_{ni} \delta_{mj} + \delta_{nj} \delta_{mi}) + \left(\zeta - \frac{2}{3} \eta \right) \delta_{nm} \delta_{ij} \right] \delta(\omega_1 + \omega_2) \end{aligned}$$

Now,

$$\mathbf{k}_1^\pm + \mathbf{k}_2^\pm = \mathbf{q}_1 \pm \frac{\pi}{d} \hat{\mathbf{z}} + \mathbf{q}_2 \pm \frac{\pi}{d} \hat{\mathbf{z}} = \mathbf{q}_1 + \mathbf{q}_2 \pm \frac{2\pi}{d} \hat{\mathbf{z}} \neq 0$$

$$\begin{aligned} \rightarrow \quad & \delta(\mathbf{k}_1^\pm + \mathbf{k}_2^\pm) = 0 \\ & \mathbf{k}_1^\pm + \mathbf{k}_2^\mp = \mathbf{q}_1 \pm \frac{\pi}{d} \hat{\mathbf{z}} + \mathbf{q}_2 \mp \frac{\pi}{d} \hat{\mathbf{z}} = \mathbf{q}_1 + \mathbf{q}_2 \end{aligned}$$

$$\rightarrow \quad \delta(\mathbf{k}_1^\pm + \mathbf{k}_2^\mp) = \delta(\mathbf{q}_1 + \mathbf{q}_2)$$

Therefore, only the cross terms in \mathfrak{S} survive so that

$$\begin{aligned} \mathfrak{S} &= -\langle S_1^+ S_2^- \rangle - \langle S_1^- S_2^+ \rangle \\ &= -4 \pi k_B T \left[k_{1n}^+ (k_{1z}^+ k_{1m}^+ - k_1^2 \delta_{mz}) k_{2i}^- (k_{2z}^- k_{2j}^- - k_2^2 \delta_{jz}) \right. \\ &\quad \left. + k_{1n}^- (k_{1z}^- k_{1m}^- - k_1^2 \delta_{mz}) k_{2i}^+ (k_{2z}^+ k_{2j}^+ - k_2^2 \delta_{jz}) \right] \\ &\quad \times \left[\eta (\delta_{ni} \delta_{mj} + \delta_{nj} \delta_{mi}) + \left(\zeta - \frac{2}{3} \eta \right) \delta_{nm} \delta_{ij} \right] \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \end{aligned}$$

Using

$$\begin{aligned} \mathbf{k}_2^\pm \Big|_{\mathbf{q}_2 \rightarrow -\mathbf{q}_1} &= (\mathbf{q}_2 \pm k_{cz} \hat{\mathbf{z}}) \Big|_{\mathbf{q}_2 \rightarrow -\mathbf{q}_1} = -(\mathbf{q}_1 \mp k_{cz} \hat{\mathbf{z}}) = -\mathbf{k}_1^\mp \\ k_{1z}^\pm &= k_{2z}^\pm = \pm \frac{\pi}{d} = \pm k_{cz} \end{aligned}$$

we get

$$\begin{aligned} \mathfrak{S} &= -4 \pi k_B T \left[k_{1n}^+ (k_{cz} k_{1m}^+ - k_1^2 \delta_{mz}) (-k_{1i}^+) (k_{cz} k_{1j}^+ - k_1^2 \delta_{jz}) \right. \\ &\quad \left. + k_{1n}^- (-k_{cz} k_{1m}^- - k_1^2 \delta_{mz}) (-k_{1i}^-) (-k_{cz} k_{1j}^- - k_1^2 \delta_{jz}) \right] \\ &\quad \times \left[\eta (\delta_{ni} \delta_{mj} + \delta_{nj} \delta_{mi}) + \left(\zeta - \frac{2}{3} \eta \right) \delta_{nm} \delta_{ij} \right] \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \end{aligned}$$

Using

$$\begin{aligned} & \left[k_{1n}^+ (k_{cz} k_{1m}^+ - k_1^2 \delta_{mz}) k_{1i}^+ (k_{cz} k_{1j}^+ - k_1^2 \delta_{jz}) \right. \\ & \quad \left. + k_{1n}^- (k_{cz} k_{1m}^- + k_1^2 \delta_{mz}) k_{1i}^- (k_{cz} k_{1j}^- + k_1^2 \delta_{jz}) \right] \delta_{ni} \delta_{mj} \\ &= k_{1n}^+ (k_{cz} k_{1m}^+ - k_1^2 \delta_{mz}) k_{1i}^+ (k_{cz} k_{1j}^+ - k_1^2 \delta_{jz}) \\ & \quad + k_{1n}^- (k_{cz} k_{1m}^- + k_1^2 \delta_{mz}) k_{1i}^- (k_{cz} k_{1j}^- + k_1^2 \delta_{jz}) \\ &= \mathbf{k}_1^+ \cdot \mathbf{k}_1^+ (k_{cz}^2 \mathbf{k}_1^+ \cdot \mathbf{k}_1^+ - 2 k_{cz} k_1^2 k_{1z}^+ + k_1^4) \\ & \quad + \mathbf{k}_1^- \cdot \mathbf{k}_1^- (k_{cz}^2 \mathbf{k}_1^- \cdot \mathbf{k}_1^- + 2 k_{cz} k_1^2 k_{1z}^- + k_1^4) \\ &= 2 k_1^2 (k_{cz}^2 k_1^2 - 2 k_{cz}^2 k_1^2 + k_1^4) \\ &= 2 k_1^4 (-k_{cz}^2 + k_1^2) \\ &= 2 k_1^4 q_1^2 \\ & \left[k_{1n}^+ (k_{cz} k_{1m}^+ - k_1^2 \delta_{mz}) k_{1i}^+ (k_{cz} k_{1j}^+ - k_1^2 \delta_{jz}) \right. \\ & \quad \left. + k_{1n}^- (k_{cz} k_{1m}^- + k_1^2 \delta_{mz}) k_{1i}^- (k_{cz} k_{1j}^- + k_1^2 \delta_{jz}) \right] \delta_{nj} \delta_{mi} \\ &= k_{1n}^+ (k_{cz} k_{1m}^+ - k_1^2 \delta_{mz}) k_{1i}^+ (k_{cz} k_{1j}^+ - k_1^2 \delta_{jz}) \\ & \quad + k_{1n}^- (k_{cz} k_{1m}^- + k_1^2 \delta_{mz}) k_{1i}^- (k_{cz} k_{1j}^- + k_1^2 \delta_{jz}) \\ &= (k_{cz} \mathbf{k}_1^+ \cdot \mathbf{k}_1^+ - k_1^2 k_{1z}^+) (k_{cz} \mathbf{k}_1^+ \cdot \mathbf{k}_1^+ - k_1^2 k_{1z}^+) \\ & \quad + (k_{cz} \mathbf{k}_1^- \cdot \mathbf{k}_1^- + k_1^2 k_{1z}^-) (k_{cz} \mathbf{k}_1^- \cdot \mathbf{k}_1^- + k_1^2 k_{1z}^-) \\ &= (k_{cz} k_1^2 - k_1^2 k_{cz}) (k_{cz} k_1^2 - k_1^2 k_{cz}) \\ & \quad + (k_{cz} k_1^2 - k_1^2 k_{cz}) (k_{cz} k_1^2 - k_1^2 k_{cz}) \\ &= 0 \end{aligned}$$

$$\begin{aligned}
 & [k_{1n}^+ (k_{Cz} k_{1m}^+ - k_1^2 \delta_{mz}) k_{1i}^+ (k_{Cz} k_{1j}^+ - k_1^2 \delta_{jz}) \\
 & \quad + k_{1n}^- (k_{Cz} k_{1m}^- + k_1^2 \delta_{mz}) k_{1i}^- (k_{Cz} k_{1j}^- + k_1^2 \delta_{jz})] \delta_{nm} \delta_{ij} \\
 = & k_{1n}^+ (k_{Cz} k_{1n}^+ - k_1^2 \delta_{nz}) k_{1j}^+ (k_{Cz} k_{1j}^+ - k_1^2 \delta_{jz}) \\
 & \quad + k_{1n}^- (k_{Cz} k_{1n}^- + k_1^2 \delta_{nz}) k_{1j}^- (k_{Cz} k_{1j}^- + k_1^2 \delta_{jz}) \\
 = & (k_{Cz} \mathbf{k}_1^+ \cdot \mathbf{k}_1^+ - k_1^2 k_{1z}^+) (k_{Cz} \mathbf{k}_1^+ \cdot \mathbf{k}_1^+ - k_1^2 k_{1z}^+) \\
 & \quad + (k_{Cz} \mathbf{k}_1^- \cdot \mathbf{k}_1^- + k_1^2 k_{1z}^-) (k_{Cz} \mathbf{k}_1^- \cdot \mathbf{k}_1^- + k_1^2 k_{1z}^-) \\
 = & (k_{Cz} k_1^2 - k_1^2 k_{Cz}) (k_{Cz} k_1^2 - k_1^2 k_{Cz}) \\
 & \quad + (k_{Cz} k_1^2 - k_1^2 k_{Cz}) (k_{Cz} k_1^2 - k_1^2 k_{Cz}) \\
 = & 0
 \end{aligned}$$

we have

$$\mathfrak{S} = 8 \pi k_B T \eta k_1^4 q_1^2 \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \quad (12.126)$$

Similarly, using [see (10.350) of §S10.F.3]

$$\langle \tilde{g}_i(\mathbf{k}, \omega) \tilde{g}_j(\mathbf{k}', \omega') \rangle = 4 \pi k_B T^2 K \delta_{ij} \delta(\mathbf{k} + \mathbf{k}') \delta(\omega + \omega')$$

we get

$$\begin{aligned}
 \mathbb{G} & = \langle (G_1^+ - G_1^-) (G_2^+ - G_2^-) \rangle \\
 & = \langle G_1^+ G_2^+ \rangle + \langle G_1^- G_2^- \rangle - \langle G_1^+ G_2^- \rangle - \langle G_1^- G_2^+ \rangle \\
 & = k_{1i}^+ k_{2j}^+ \langle \tilde{g}_{si}(\mathbf{k}_1^+, \omega_1) \tilde{g}_{sj}(\mathbf{k}_2^+, \omega_2) \rangle + k_{1i}^- k_{2j}^- \langle \tilde{g}_{si}(\mathbf{k}_1^-, \omega_1) \tilde{g}_{sj}(\mathbf{k}_2^-, \omega_2) \rangle \\
 & \quad - k_{1i}^+ k_{2j}^- \langle \tilde{g}_{si}(\mathbf{k}_1^+, \omega_1) \tilde{g}_{sj}(\mathbf{k}_2^-, \omega_2) \rangle - k_{1i}^- k_{2j}^+ \langle \tilde{g}_{si}(\mathbf{k}_1^-, \omega_1) \tilde{g}_{sj}(\mathbf{k}_2^+, \omega_2) \rangle \\
 & = -\langle G_1^+ G_2^- \rangle - \langle G_1^- G_2^+ \rangle \\
 & = -4 \pi k_B T^2 K \delta_{ij} (k_{1i}^+ k_{2j}^- + k_{1i}^- k_{2j}^+) \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \\
 & = 4 \pi k_B T^2 K \delta_{ij} (k_{1i}^+ k_{1j}^+ + k_{1i}^- k_{1j}^-) \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \\
 & = 4 \pi k_B T^2 K (\mathbf{k}_1^+ \cdot \mathbf{k}_1^+ + \mathbf{k}_1^- \cdot \mathbf{k}_1^-) \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \\
 & = 8 \pi k_B T^2 K k_1^2 \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \quad (12.127a)
 \end{aligned}$$

(12.125) thus becomes

$$\begin{aligned}
 & \langle \tilde{u}_{q_1}(\omega_1) \tilde{u}_{q_2}(\omega_2) \rangle \\
 = & \frac{1}{4(i\lambda_{s1} + \omega_1)(i\lambda_{s2} + \omega_2)} \left[\frac{1}{k_1^2 k_2^2 \rho_0^2} (\langle S_1^+ S_2^- \rangle + \langle S_1^- S_2^+ \rangle) \right. \\
 & \quad \left. + \frac{v_t^2 K_c^A}{a^2 \rho_0^2 \tilde{c}_\rho^2} (\langle G_1^+ G_2^- \rangle + \langle G_1^- G_2^+ \rangle) \right] \quad (12.128)
 \end{aligned}$$

$$\begin{aligned}
 = & \frac{-1}{4(i\lambda_{s1} + \omega_1)(i\lambda_{s2} + \omega_2)} \left(\frac{8 \pi k_B T \eta k_1^4 q_1^2}{k_1^2 k_2^2 \rho_0^2} \right. \\
 & \quad \left. + \frac{8 \pi k_B T^2 K k_1^2 v_t^2 K_c^A}{a^2 \rho_0^2 \tilde{c}_\rho^2} \right) \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2)
 \end{aligned}$$

$$= \frac{2 \pi k_B T \eta q_1^2}{\rho_0^2 (\lambda_{s1}^2 + \omega_1^2)} \left(1 + \frac{TK k_1^2 v_t^2 K_c^A}{a^2 \tilde{c}_\rho^2 \eta q_1^2} \right) \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2)$$

$$= \frac{A}{\lambda_{s1}^2 + \omega_1^2} \delta(\mathbf{q}_1 + \mathbf{q}_2) \delta(\omega_1 + \omega_2) \quad (12.129)$$

where

$$\begin{aligned}
A &= \frac{2 \pi k_B T \eta q_1^2}{\rho_0^2} \left(1 + \frac{TK k_1^2 v_t^2 k_c^4}{a^2 \tilde{c}_\rho^2 \eta q_1^2} \right) \\
&= \frac{2 \pi k_B T v_t q_1^2}{\rho_0} \left(1 + \frac{TV_t^2 k_c^4 k_1^2}{a^2 \tilde{c}_\rho \mathcal{P} q_1^2} \right)
\end{aligned}$$

Near the critical point,

$$q_1^2 \approx q_c^2 \quad \rightarrow \quad k_1^2 \approx k_c^2 = 3 q_c^2$$

we have

$$A \approx A_c = \frac{2 \pi k_B T v_t q_c^2}{\rho_0} \left(1 + \frac{3 T v_t^2 k_c^4}{a^2 \tilde{c}_\rho \mathcal{P}} \right) \quad (12.130)$$

Now, as shown in (10.324) of §S10.F.2,

$$\langle \tilde{X}_{k_1}(\omega_1) \tilde{X}_{k_2}(\omega_2) \rangle = 2 \pi V \delta(\mathbf{k}_1 + \mathbf{k}_2) \delta(\omega_1 + \omega_2) \int_{-\infty}^{\infty} d\tau e^{-i\omega_1 \tau} \langle \tilde{X}_{k_1}(\tau) \tilde{X}_{k_2}(0) \rangle$$

so that (12.129) implies

$$\frac{A}{\lambda_{s1}^2 + \omega_1^2} = 2 \pi V \int_{-\infty}^{\infty} d\tau e^{-i\omega_1 \tau} \langle \tilde{u}_{q_1}(\tau) \tilde{u}_{-q_1}(0) \rangle \quad (12.131)$$

Taking the inverse transform, we get

$$\begin{aligned}
\int_{-\infty}^{\infty} \frac{d\omega_1}{2\pi} e^{i\omega_1 \tau'} \frac{A}{\lambda_{s1}^2 + \omega_1^2} &= 2 \pi V \int_{-\infty}^{\infty} \frac{d\omega_1}{2\pi} e^{i\omega_1 \tau'} \int_{-\infty}^{\infty} d\tau e^{-i\omega_1 \tau} \langle \tilde{u}_{q_1}(\tau) \tilde{u}_{-q_1}(0) \rangle \\
&= 2 \pi V \int_{-\infty}^{\infty} d\tau \delta(\tau' - \tau) \langle \tilde{u}_{q_1}(\tau) \tilde{u}_{-q_1}(0) \rangle \\
&= 2 \pi V \langle \tilde{u}_{q_1}(\tau') \tilde{u}_{-q_1}(0) \rangle
\end{aligned}$$

$$\rightarrow \langle \tilde{u}_{q_1}(\tau) \tilde{u}_{-q_1}(0) \rangle = \frac{A}{(2\pi)^2 V} \int_{-\infty}^{\infty} d\omega_1 \frac{e^{i\omega_1 \tau}}{\lambda_{s1}^2 + \omega_1^2}$$

The integral can be evaluated as a contour integral. For $\tau > 0$, we must close the contour in the upper-half of the complex ω_1 plane, thus enclosing the pole at $\omega_1 = i\lambda_{s1}$. Hence,

$$\begin{aligned}
\langle \tilde{u}_{q_1}(\tau) \tilde{u}_{-q_1}(0) \rangle &= \frac{A}{(2\pi)^2 V} 2\pi i \text{Res} \left(\frac{e^{i\omega_1 \tau}}{\lambda_{s1}^2 + \omega_1^2}; \omega_1 = i\lambda_{s1} \right) \\
&= \frac{A}{4\pi V} \frac{e^{-\lambda_{s1} \tau}}{\lambda_{s1}} \quad (12.132)
\end{aligned}$$

As one approaches the critical point, $\lambda_{s1} \rightarrow \lambda_s^c = 0$ so that the exponential factor $e^{-\lambda_{s1} \tau}$ takes longer and longer to die away, while the $\frac{1}{\lambda_{s1}}$ factor diverges. This means the linear analysis we have been considering actually breaks down as $\lambda_{s1} \rightarrow \lambda_s^c$. In other words, non-linear effects must be included in the study of fluctuations close to the critical point.

Exercise 12.4.

The Fourier amplitude

$$u_{\mathbf{k}}(t) = \int d^3 r e^{-i\mathbf{k} \cdot \mathbf{r}} u(\mathbf{r}, t) \quad (0a)$$

of a fluctuating mode $u(r, t)$ in a non-equilibrium system of volume V is assumed to satisfy a time-dependent Ginzburg-Landau equation

$$\frac{d u_k(t)}{d t} = - \frac{\delta F(t)}{\delta u_k^*(t)} + \eta_k(t) \quad (0b)$$

where F is the free energy and η_k is a random noise governed by the conditions

$$\langle \eta_k(t) \rangle = 0$$

and

$$\begin{aligned} \langle \eta_{k_1}(t_1) \eta_{k_2}(t_2) \rangle &= \Gamma_{k_1} \delta_{k_1, -k_2} \delta(t_1 - t_2) \\ &= \Gamma_{k_1} \frac{(2\pi)^3}{V} \delta(\mathbf{k}_1 + \mathbf{k}_2) \delta(t_1 - t_2) \end{aligned} \quad (0c)$$

where the average is over all possible values of η_k .

In the Gaussian approximation,

$$F(t) = \int d^3 k \lambda_k u_k^*(t) u_k(t) \quad (0d)$$

The complex $u_k(t)$ represents two independent (real) variables, which can be taken either as $\{\text{Re } u_k(t), \text{Im } u_k(t)\}$, or $\{u_k(t), u_k^*(t)\}$. Choosing the latter gives the basic relations of the variational derivatives as

$$\frac{\delta u_{k_1}(t)}{\delta u_{k_2}(t)} = \delta(\mathbf{k}_1 - \mathbf{k}_2) = \frac{\delta u_{k_1}^*(t)}{\delta u_{k_2}^*(t)} \quad \frac{\delta u_{k_1}^*(t)}{\delta u_{k_2}(t)} = 0 \quad (0e)$$

Since $u(r, t)$ & $\eta(r, t)$ must be real, we also have

$$u_k^*(t) = u_{-k}(t) \quad \eta_k^*(t) = \eta_{-k}(t) \quad (0f)$$

Assume the medium is isotropic and the correlation functions are stationary (time translation invariant) but not time reversal invariant (since we are far from equilibrium). What is the strength Γ_k of the random noise?

Answer

Consider the equation of motion

$$\dot{u}_k(t) = -\lambda_k u_k(t) + \eta_k(t) \quad (1)$$

Taking the complex conjugate, we have

$$\dot{u}_k^*(t) = -\lambda_k^* u_k^*(t) + \eta_k^*(t) \quad (1a)$$

If we put in the reality condition

$$u_k^*(t) = u_{-k}(t)$$

(1a) becomes

$$\dot{u}_{-k}(t) = -\lambda_k^* u_{-k}(t) + \eta_k^*(t)$$

Comparing this with the $k \rightarrow -k$ version of (1g) gives

$$\lambda_{-k} = \lambda_k^* \quad \eta_{-k}(t) = \eta_k^*(t) \quad (1b)$$

which means $\eta(r, t)$ is real, as it should be.

Taking the Fourier transform of (1) & (1a) gives

$$\begin{aligned} -i \omega \tilde{u}_k(\omega) &= -\lambda_k \tilde{u}_k(\omega) + \tilde{\eta}_k(\omega) \\ i \omega \tilde{u}_k^*(\omega) &= -\lambda_k^* \tilde{u}_k^*(\omega) + \tilde{\eta}_k^*(\omega) \end{aligned}$$

where

$$\begin{aligned} u_{\mathbf{k}}(t) &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{-i\omega t} \tilde{u}_{\mathbf{k}}(\omega) & \eta_{\mathbf{k}}(t) &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{-i\omega t} \tilde{\eta}_{\mathbf{k}}(\omega) \\ u_{\mathbf{k}}^*(t) &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{i\omega t} \tilde{u}_{\mathbf{k}}^*(\omega) & \eta_{\mathbf{k}}^*(t) &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{i\omega t} \tilde{\eta}_{\mathbf{k}}^*(\omega) \end{aligned}$$

Hence,

$$\tilde{u}_{\mathbf{k}}(\omega) = \frac{1}{-i\omega + \lambda_{\mathbf{k}}} \tilde{\eta}_{\mathbf{k}}(\omega) \quad (1c)$$

$$\tilde{u}_{\mathbf{k}}^*(\omega) = \frac{1}{i\omega + \lambda_{\mathbf{k}}^*} \tilde{\eta}_{\mathbf{k}}^*(\omega) \quad (1d)$$

Taking $(\mathbf{k}, \omega) \rightarrow -(\mathbf{k}, \omega)$ on (1c) gives

$$\tilde{u}_{-\mathbf{k}}(-\omega) = \frac{1}{i\omega + \lambda_{-\mathbf{k}}} \tilde{\eta}_{-\mathbf{k}}(-\omega)$$

which can be compared with (1d) to give

$$\tilde{u}_{\mathbf{k}}^*(\omega) = \tilde{u}_{-\mathbf{k}}(-\omega) \quad \tilde{\eta}_{\mathbf{k}}^*(\omega) = \tilde{\eta}_{-\mathbf{k}}(-\omega) \quad (1e)$$

as expected from the reality of $u(\mathbf{r}, t)$ and $\eta(\mathbf{r}, t)$.

From (1c), we get

$$\langle \tilde{u}_{\mathbf{k}_1}(\omega_1) \tilde{u}_{\mathbf{k}_2}(\omega_2) \rangle = \frac{1}{(-i\omega_1 + \lambda_{\mathbf{k}_1})(-i\omega_2 + \lambda_{\mathbf{k}_2})} \langle \tilde{\eta}_{\mathbf{k}_1}(\omega_1) \tilde{\eta}_{\mathbf{k}_2}(\omega_2) \rangle \quad (1f)$$

From (0c), we have [see (5.78) of §5.E.1]

$$\begin{aligned} \langle \eta_{\mathbf{k}_1}(t_1) \eta_{\mathbf{k}_2}(t_2) \rangle &= \Gamma_{\mathbf{k}_1} \delta_{\mathbf{k}_1, -\mathbf{k}_2} \delta(t_1 - t_2) \\ &= \Gamma_{\mathbf{k}_1} \delta_{\mathbf{k}_1, -\mathbf{k}_2} \int \frac{d\omega_1}{2\pi} e^{-i\omega_1(t_1 - t_2)} \end{aligned} \quad (1g)$$

$$= \int \frac{d\omega_1}{2\pi} \int \frac{d\omega_2}{2\pi} e^{-i\omega_1 t_1 - i\omega_2 t_2} \langle \tilde{\eta}_{\mathbf{k}_1}(\omega_1) \tilde{\eta}_{\mathbf{k}_2}(\omega_2) \rangle \quad (1h)$$

Consider now the correlation function

$$C_{uu}(\mathbf{r}_1, t_1; \mathbf{r}_2, t_2) \equiv \langle u(\mathbf{r}_1, t_1) u(\mathbf{r}_2, t_2) \rangle \quad (2a)$$

where the thermal average is simulated by the average over η . Taking the Fourier transform in space, we have

$$C_{uu}(\mathbf{k}_1, t_1; \mathbf{k}_2, t_2) \equiv \langle u_{\mathbf{k}_1}(t_1) u_{\mathbf{k}_2}(t_2) \rangle \quad (2b)$$

whose equation of motion can be obtained from (1) as follows. To begin, (1) $\times u_{\mathbf{k}'}(t')$ gives

$$\begin{aligned} \frac{d u_{\mathbf{k}}(t)}{d t} u_{\mathbf{k}'}(t') &= -\lambda_{\mathbf{k}} u_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') + \eta_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \\ \rightarrow \frac{d}{d t} \langle u_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \rangle &= -\lambda_{\mathbf{k}} \langle u_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \rangle + \langle \eta_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \rangle \end{aligned} \quad (2c)$$

$$\frac{d}{d t} C_{uu}(\mathbf{k}, t; \mathbf{k}', t') = -\lambda_{\mathbf{k}} C_{uu}(\mathbf{k}, t; \mathbf{k}', t') + \langle \eta_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \rangle \quad (2d)$$

Now,

$$\langle \eta_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \rangle = \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{-i\omega t'} \langle \eta_{\mathbf{k}}(t) \tilde{u}_{\mathbf{k}'}(\omega) \rangle$$

$$\begin{aligned}
 &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} \frac{e^{-i\omega t'}}{-i\omega + \lambda_{k'}} \langle \eta_k(t) \tilde{\eta}_{k'}(\omega) \rangle && \text{[(1c) used.]} \\
 &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} \frac{e^{-i\omega t'}}{-i\omega + \lambda_{k'}} \int_{-\infty}^{\infty} dt'' e^{i\omega t''} \langle \eta_k(t) \eta_{k'}(t'') \rangle \\
 &= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} \frac{e^{-i\omega t'}}{-i\omega + \lambda_{k'}} \int_{-\infty}^{\infty} dt'' e^{i\omega t''} \delta_{k,-k'} \Gamma_k \delta(t-t'') && \text{[(0c) used.]} \\
 &= -\delta_{k,-k'} \Gamma_k \int_{-\infty}^{\infty} \frac{d\omega}{2\pi i} \frac{e^{i\omega(t-t')}}{\omega + i\lambda_{-k}} && (2e)
 \end{aligned}$$

For $t - t' > 0$, the contour must close in the upper ω -plane, hence

$$\int_{-\infty}^{\infty} \frac{d\omega}{2\pi i} \frac{e^{i\omega(t-t')}}{\omega + i\lambda_{-k}} = \begin{cases} e^{\lambda_{-k}(t-t')} & \text{if } \text{Re } \lambda_{-k} < 0 \\ 0 & \text{if } \text{Re } \lambda_{-k} > 0 \end{cases}$$

Reminder:

$$\lambda_{-k} = \lambda_k^* \quad \rightarrow \quad \text{Re } \lambda_{-k} = \text{Re } \lambda_k$$

For $t - t' < 0$, the contour must close in the lower ω -plane, hence

$$\int_{-\infty}^{\infty} \frac{d\omega}{2\pi i} \frac{e^{i\omega(t-t')}}{\omega + i\lambda_{-k}} = \begin{cases} 0 & \text{if } \text{Re } \lambda_{-k} < 0 \\ -e^{\lambda_{-k}(t-t')} & \text{if } \text{Re } \lambda_{-k} > 0 \end{cases}$$

For $t - t' = 0$, we have

$$\begin{aligned}
 \int_{-\infty}^{\infty} \frac{d\omega}{2\pi i} \frac{1}{\omega + i\lambda_{-k}} &= \frac{1}{2\pi i} \ln(\omega + i\lambda_{-k}) \Big|_{-\infty}^{\infty} \\
 &= \frac{1}{2\pi i} \lim_{\omega \rightarrow \infty} [\ln \omega - \ln(-\omega)] \\
 &= \frac{1}{2\pi i} \lim_{\omega \rightarrow \infty} [\ln \omega - \ln(e^{\pm i\pi} \omega)] \\
 &= \mp \frac{1}{2} && (2f)
 \end{aligned}$$

where the sign before $\frac{1}{2}$ is arbitrary at this point.

(2e) thus becomes

$$\begin{aligned}
 \langle \eta_k(t) u_{k'}(t') \rangle &= -\delta_{k,-k'} \Gamma_k \theta(t-t') e^{\lambda_{-k}(t-t')} && \text{if } \text{Re } \lambda_{-k} < 0 \\
 \langle \eta_k(t) u_{k'}(t') \rangle &= \delta_{k,-k'} \Gamma_k \theta(t'-t) e^{-\lambda_{-k}(t'-t)} && \text{if } \text{Re } \lambda_{-k} > 0 \\
 \langle \eta_k(t') u_{k'}(t') \rangle &= \pm \frac{1}{2} \delta_{k,-k'} \Gamma_k
 \end{aligned}$$

Setting

$$\tau = t - t' s_k = \text{sgn}(\text{Re } \lambda_k) \quad \Theta(\tau) = \begin{cases} 1 & \text{if } \tau > 0 \\ \frac{1}{2} & \text{if } \tau = 0 \\ 0 & \text{if } \tau < 0 \end{cases}$$

we can combine these results to get

$$\langle \eta_k(t) u_{k'}(t') \rangle = s_k \delta_{k,-k'} \Gamma_k \Theta(-s_k \tau) e^{\lambda_{-k} \tau} \quad (2g)$$

where the sign in (2f) is now determined by s_k .

(2d) thus becomes

$$\frac{d}{d\tau} C_{uu}(\mathbf{k}, \mathbf{k}'; \tau) = -\lambda_{\mathbf{k}} C_{uu}(\mathbf{k}, \mathbf{k}'; \tau) + s_{\mathbf{k}} \delta_{\mathbf{k}, -\mathbf{k}'} \Gamma_{\mathbf{k}} \Theta(-s_{\mathbf{k}} \tau) e^{\lambda_{-\mathbf{k}} \tau} \quad (2h)$$

with solution

$$C_{uu}(\mathbf{k}, \mathbf{k}'; \tau) = \left[A \Theta(s_{\mathbf{k}} \tau) e^{-\lambda_{\mathbf{k}} \tau} + B \Theta(-s_{\mathbf{k}} \tau) \delta_{\mathbf{k}, -\mathbf{k}'} e^{\lambda_{-\mathbf{k}} \tau} \right] \quad (2j)$$

where A & B are constants to be determined.

Putting (2j) back into (2h) gives

$$\begin{aligned} & s_{\mathbf{k}} \delta(\tau) (A - B \delta_{\mathbf{k}, -\mathbf{k}'}) - A \Theta(s_{\mathbf{k}} \tau) \lambda_{\mathbf{k}} e^{-\lambda_{\mathbf{k}} \tau} + B \Theta(-s_{\mathbf{k}} \tau) \delta_{\mathbf{k}, -\mathbf{k}'} \lambda_{-\mathbf{k}} e^{\lambda_{-\mathbf{k}} \tau} \\ &= -\lambda_{\mathbf{k}} \left[A \Theta(s_{\mathbf{k}} \tau) e^{-\lambda_{\mathbf{k}} \tau} + B \Theta(-s_{\mathbf{k}} \tau) \delta_{\mathbf{k}, -\mathbf{k}'} e^{\lambda_{-\mathbf{k}} \tau} \right] + s_{\mathbf{k}} \delta_{\mathbf{k}, -\mathbf{k}'} \Gamma_{\mathbf{k}} \Theta(-s_{\mathbf{k}} \tau) e^{\lambda_{-\mathbf{k}} \tau} \end{aligned}$$

The coefficients of $\delta(\tau)$, $\Theta(s_{\mathbf{k}} \tau)$ and $\Theta(-s_{\mathbf{k}} \tau)$ must vanish separately, giving

$$\begin{aligned} A - B \delta_{\mathbf{k}, -\mathbf{k}'} &= 0 \\ B \lambda_{-\mathbf{k}} &= -\lambda_{\mathbf{k}} B + s_{\mathbf{k}} \Gamma_{\mathbf{k}} \end{aligned}$$

which can be solved to give

$$B = s_{\mathbf{k}} \frac{\Gamma_{\mathbf{k}}}{\lambda_{\mathbf{k}} + \lambda_{-\mathbf{k}}} \quad A = s_{\mathbf{k}} \delta_{\mathbf{k}, -\mathbf{k}'} \frac{\Gamma_{\mathbf{k}}}{\lambda_{\mathbf{k}} + \lambda_{-\mathbf{k}}}$$

so that (2j) becomes

$$C_{uu}(\mathbf{k}, \mathbf{k}'; \tau) = s_{\mathbf{k}} \delta_{\mathbf{k}, -\mathbf{k}'} \frac{\Gamma_{\mathbf{k}}}{\lambda_{\mathbf{k}} + \lambda_{-\mathbf{k}}} \left[\Theta(s_{\mathbf{k}} \tau) e^{-\lambda_{\mathbf{k}} \tau} + \Theta(-s_{\mathbf{k}} \tau) e^{\lambda_{-\mathbf{k}} \tau} \right] \quad (2k)$$

Setting $\tau = 0$ then gives

$$\begin{aligned} C_{uu}(\mathbf{k}, \mathbf{k}'; 0) &= s_{\mathbf{k}} \delta_{\mathbf{k}, -\mathbf{k}'} \frac{\Gamma_{\mathbf{k}}}{\lambda_{\mathbf{k}} + \lambda_{-\mathbf{k}}} \\ &= \delta_{\mathbf{k}, -\mathbf{k}'} \frac{\Gamma_{\mathbf{k}}}{2 |\operatorname{Re} \lambda_{\mathbf{k}}|} \end{aligned} \quad (2m)$$

so that

$$\begin{aligned} \Gamma_{\mathbf{k}} &= s_{\mathbf{k}} (\lambda_{\mathbf{k}} + \lambda_{-\mathbf{k}}) C_{uu}(\mathbf{k}, -\mathbf{k}; 0) \\ &= 2 |\operatorname{Re} \lambda_{\mathbf{k}}| C_{uu}(\mathbf{k}, -\mathbf{k}; 0) \end{aligned} \quad (9)$$

and

$$C_{uu}(\mathbf{k}, \mathbf{k}'; \tau) = C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \left[\Theta(s_{\mathbf{k}} \tau) e^{-\lambda_{\mathbf{k}} \tau} + \Theta(-s_{\mathbf{k}} \tau) e^{\lambda_{-\mathbf{k}} \tau} \right] \quad (2n)$$

The Fourier transform components are given by

$$\langle \tilde{u}_{\mathbf{k}}(\omega) \tilde{u}_{\mathbf{k}'}(\omega') \rangle = \int_{-\infty}^{\infty} dt e^{i\omega t} \int_{-\infty}^{\infty} dt' e^{i\omega' t'} \langle u_{\mathbf{k}}(t) u_{\mathbf{k}'}(t') \rangle$$

Setting

$$\tau = t - t' \quad T = \frac{1}{2} (t + t')$$

$$\rightarrow \quad t = T + \frac{1}{2} \tau \quad t' = T - \frac{1}{2} \tau$$

we have

$$d\tau dT = \begin{vmatrix} 1 & -1 \\ \frac{1}{2} & \frac{1}{2} \end{vmatrix} dt dt' = dt dt'$$

$$\omega t + \omega' t' = (\omega + \omega') T + \frac{1}{2} (\omega - \omega') \tau$$

so that

$$\begin{aligned} \langle \tilde{u}_k(\omega) \tilde{u}_{k'}(\omega') \rangle &= \int_{-\infty}^{\infty} dT e^{i(\omega + \omega')T} \int_{-\infty}^{\infty} d\tau e^{i(\omega - \omega')\tau/2} \langle u_k(t) u_{k'}(t') \rangle \\ &= 2\pi \delta(\omega + \omega') \int_{-\infty}^{\infty} d\tau e^{i\omega\tau} C_{uu}(\mathbf{k}, \mathbf{k}'; \tau) \\ &= 2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \int_{-\infty}^{\infty} d\tau e^{i\omega\tau} \left[\Theta(s_k \tau) e^{-\lambda_k \tau} + \Theta(-s_k \tau) e^{\lambda_{-k} \tau} \right] \end{aligned}$$

For $s_k = 1$, we have $\text{Re } \lambda_k > 0$ and

$$\begin{aligned} \langle \tilde{u}_k(\omega) \tilde{u}_{k'}(\omega') \rangle &= 2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \\ &\quad \times \left[\int_0^{\infty} d\tau e^{i\omega\tau} e^{-\lambda_k \tau} + \int_{-\infty}^0 d\tau e^{i\omega\tau} e^{\lambda_{-k} \tau} \right] \\ &= 2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \left(-\frac{1}{i\omega - \lambda_k} + \frac{1}{i\omega + \lambda_{-k}} \right) \quad (7) \\ &= -2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \frac{\lambda_k + \lambda_{-k}}{(i\omega - \lambda_k)(i\omega + \lambda_{-k})} \\ &= -2\pi \delta(\omega + \omega') \delta_{k, -k'} \frac{\Gamma_k}{(i\omega - \lambda_k)(i\omega + \lambda_{-k})} \quad [(2m) \text{ used.}] \end{aligned}$$

For $s_k = -1$, we have $\text{Re } \lambda_k < 0$ and

$$\begin{aligned} \langle \tilde{u}_k(\omega) \tilde{u}_{k'}(\omega') \rangle &= 2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \\ &\quad \times \left[\int_{-\infty}^0 d\tau e^{i\omega\tau} e^{-\lambda_k \tau} + \int_0^{\infty} d\tau e^{i\omega\tau} e^{\lambda_{-k} \tau} \right] \\ &= 2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \left(\frac{1}{i\omega - \lambda_k} - \frac{1}{i\omega + \lambda_{-k}} \right) \\ &= 2\pi \delta(\omega + \omega') C_{uu}(\mathbf{k}, \mathbf{k}'; 0) \frac{\lambda_k + \lambda_{-k}}{(i\omega - \lambda_k)(i\omega + \lambda_{-k})} \\ &= -2\pi \delta(\omega + \omega') \delta_{k, -k'} \frac{\Gamma_k}{(i\omega - \lambda_k)(i\omega + \lambda_{-k})} \quad [(2m) \text{ used.}] \end{aligned}$$

Hence, for both cases

$$\langle \tilde{u}_k(\omega) \tilde{u}_{k'}(\omega') \rangle = -2\pi \delta(\omega + \omega') \delta_{k, -k'} \frac{\Gamma_k}{(i\omega - \lambda_k)(i\omega + \lambda_{-k})} \quad (2p)$$

Hence,

$$\begin{aligned} \langle \tilde{\eta}_{k_1}(\omega_1) \tilde{\eta}_{k_2}(\omega_2) \rangle &= (-i\omega_1 + \lambda_{k_1})(-i\omega_2 + \lambda_{k_2}) \langle \tilde{u}_{k_1}(\omega_1) \tilde{u}_{k_2}(\omega_2) \rangle \\ &= -2\pi \delta(\omega_1 + \omega_2) \delta_{k_1, -k_2} \Gamma_{k_1} \frac{(-i\omega_1 + \lambda_{k_1})(-i\omega_2 + \lambda_{k_2})}{(i\omega_1 - \lambda_{k_1})(i\omega_1 + \lambda_{-k_1})} \\ &= 2\pi \delta(\omega_1 + \omega_2) \delta_{k_1, -k_2} \Gamma_{k_1} \\ &= 2\pi \delta(\omega_1 + \omega_2) \delta_{k_1, -k_2} s_k(\lambda_{k_1} + \lambda_{-k_1}) C_{uu}(\mathbf{k}_1, -\mathbf{k}_1; 0) \quad (8) \end{aligned}$$

Thus,

$$\langle \eta_{k_1}(t_1) \eta_{k_2}(t_2) \rangle = \int \frac{d\omega_1}{2\pi} \int \frac{d\omega_2}{2\pi} e^{-i\omega_1 t_1 - i\omega_2 t_2} \langle \tilde{\eta}_{k_1}(\omega_1) \tilde{\eta}_{k_2}(\omega_2) \rangle$$

$$\begin{aligned}
&= \delta_{\mathbf{k}_1, -\mathbf{k}_2} \Gamma_{\mathbf{k}_1} \int \frac{d\omega_1}{2\pi} e^{-i\omega_1(t_1 - t_2)} \\
&= \delta_{\mathbf{k}_1, -\mathbf{k}_2} \Gamma_{\mathbf{k}_1} \delta(t_1 - t_2)
\end{aligned}$$

in agreement with (0c).

Comment

The equation of motion (1) can be derived from the action

$$S = \int dt L$$

with the Lagrangian

$$L = \int d^3 k \left[-\dot{u}_{\mathbf{k}}(t) u_{\mathbf{k}}^*(t) - \lambda_{\mathbf{k}} u_{\mathbf{k}}^*(t) u_{\mathbf{k}}(t) + u_{\mathbf{k}}^*(t) \eta_{\mathbf{k}}(t) - \eta_{\mathbf{k}}^*(t) u_{\mathbf{k}}(t) \right]$$

where

$$\dot{u}_{\mathbf{k}}(t) = \frac{d u_{\mathbf{k}}}{d t}$$

and the signs for various terms are chosen to reproduce (1) and its variants in a self-consistent manner [see below].

Using (0e), we have

$$\begin{aligned}
\frac{\delta L}{\delta \dot{u}_{\mathbf{k}}^*(t)} &= 0 \\
\frac{\delta L}{\delta u_{\mathbf{k}}^*(t)} &= \int d^3 k' \left[-\dot{u}_{\mathbf{k}'}(t) \delta(\mathbf{k} - \mathbf{k}') - \lambda_{\mathbf{k}'} \delta(\mathbf{k} - \mathbf{k}') u_{\mathbf{k}'}(t) + \delta(\mathbf{k} - \mathbf{k}') \eta_{\mathbf{k}'}(t) \right] \\
&= -\dot{u}_{\mathbf{k}}(t) - \lambda_{\mathbf{k}} u_{\mathbf{k}}(t) + \eta_{\mathbf{k}}(t)
\end{aligned}$$

so that the Euler-Lagrange equation for $u_{\mathbf{k}}^*(t)$,

$$\frac{\delta L}{\delta u_{\mathbf{k}}^*(t)} - \frac{d}{d t} \frac{\delta L}{\delta \dot{u}_{\mathbf{k}}^*(t)} = 0$$

becomes

$$\dot{u}_{\mathbf{k}}(t) = -\lambda_{\mathbf{k}} u_{\mathbf{k}}(t) + \eta_{\mathbf{k}}(t) \quad (\text{a})$$

which is just (1).

For $u_{\mathbf{k}}(t)$, we have

$$\begin{aligned}
\frac{\delta L}{\delta \dot{u}_{\mathbf{k}}(t)} &= \int d^3 k' u_{\mathbf{k}'}^*(t) \delta(\mathbf{k} - \mathbf{k}') = -u_{\mathbf{k}}^*(t) \\
\frac{\delta L}{\delta u_{\mathbf{k}}(t)} &= \int d^3 k' \left[-\lambda_{\mathbf{k}'} u_{\mathbf{k}'}^*(t) \delta(\mathbf{k} - \mathbf{k}') - \eta_{\mathbf{k}'}^*(t) \delta(\mathbf{k} - \mathbf{k}') \right] \\
&= -\lambda_{\mathbf{k}} u_{\mathbf{k}}^*(t) - \eta_{\mathbf{k}}^*(t)
\end{aligned}$$

so that the E-L equation for $u_{\mathbf{k}}(t)$,

$$\frac{\delta L}{\delta u_{\mathbf{k}}(t)} - \frac{d}{d t} \frac{\delta L}{\delta \dot{u}_{\mathbf{k}}(t)} = 0$$

becomes

$$\dot{u}_{\mathbf{k}}^*(t) = \lambda_{\mathbf{k}} u_{\mathbf{k}}^*(t) + \eta_{\mathbf{k}}^*(t) \quad (\text{b})$$

Comparing (b) with the complex conjugate of (a) gives

$$\lambda_k^* = -\lambda_k$$

so that λ_k is purely imaginary.

Since the results in §Answer require $\text{Re } \lambda_k \neq 0$, we conclude those results cannot be derived from a Lagrangian formalism.